

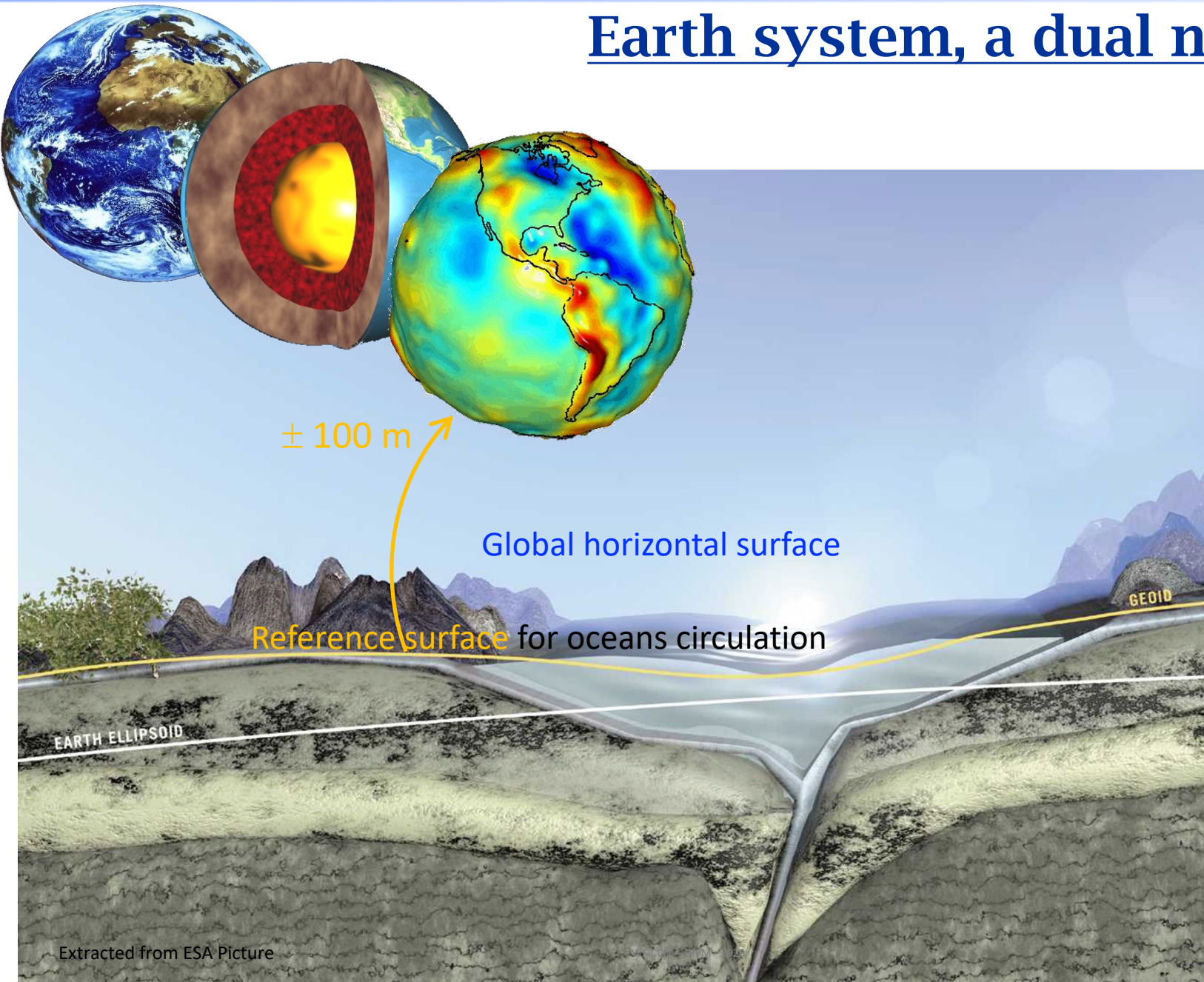
Atomic sensors metrology for long term and trustable monitoring of climate change Key Geodetic Parameters

S. Merlet

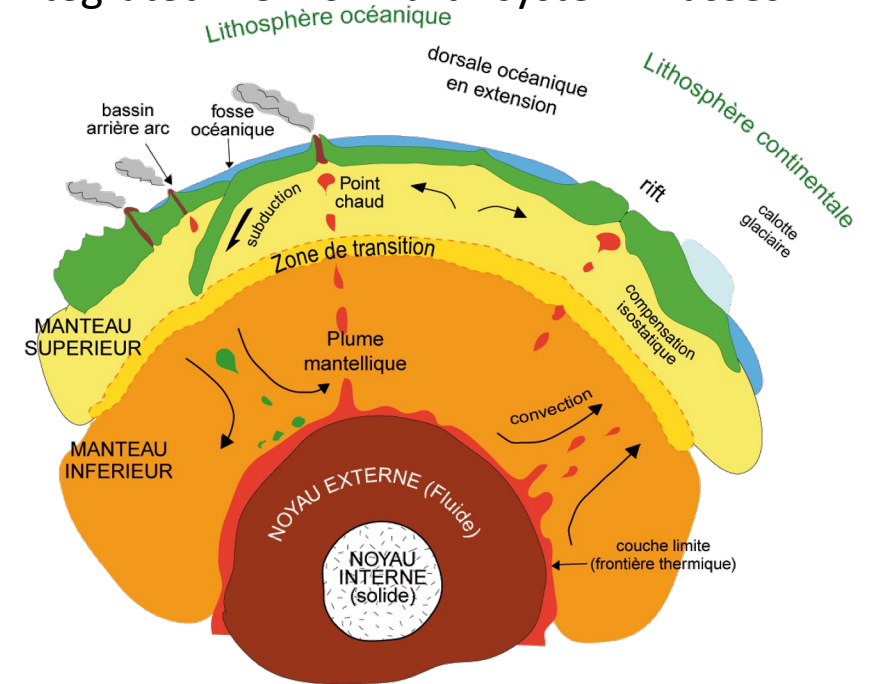
LNE-SYRTE, Observatoire de Paris, Université PSL, CNRS, Sorbonne Université, Paris, France

<https://syрте.obspm.fr/spip/science/iaci/>

Earth system, a dual nature



Integrated view on Earth system masses



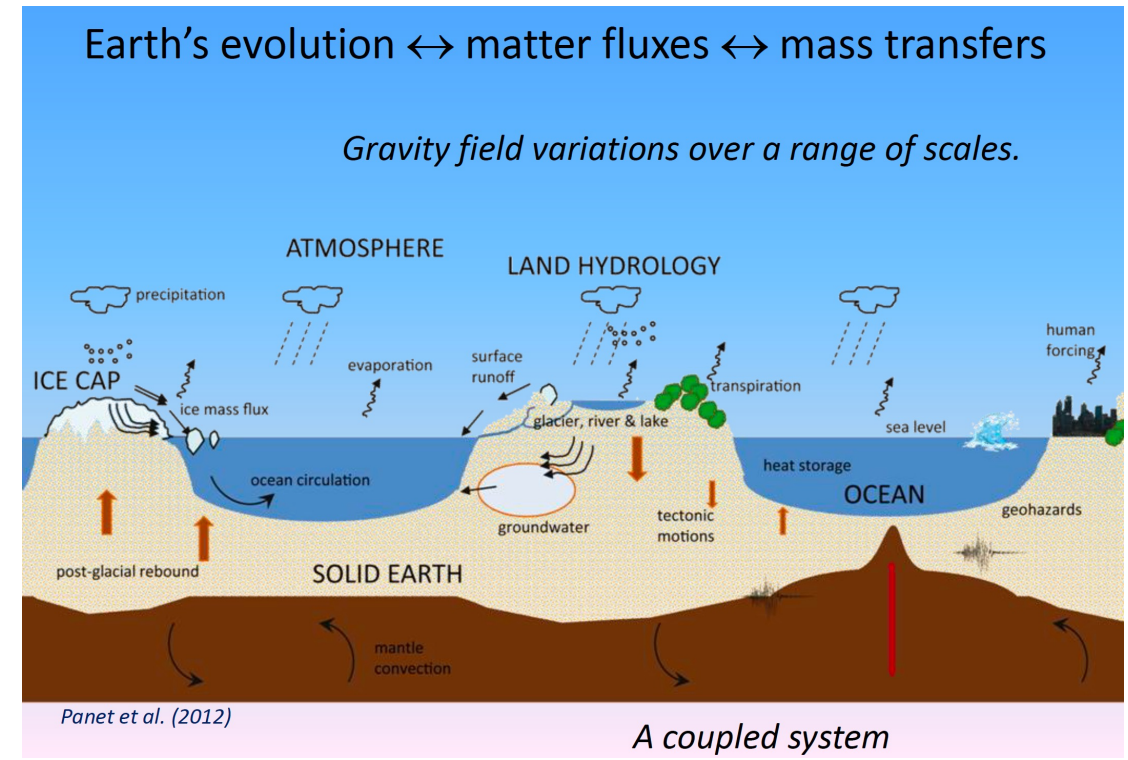
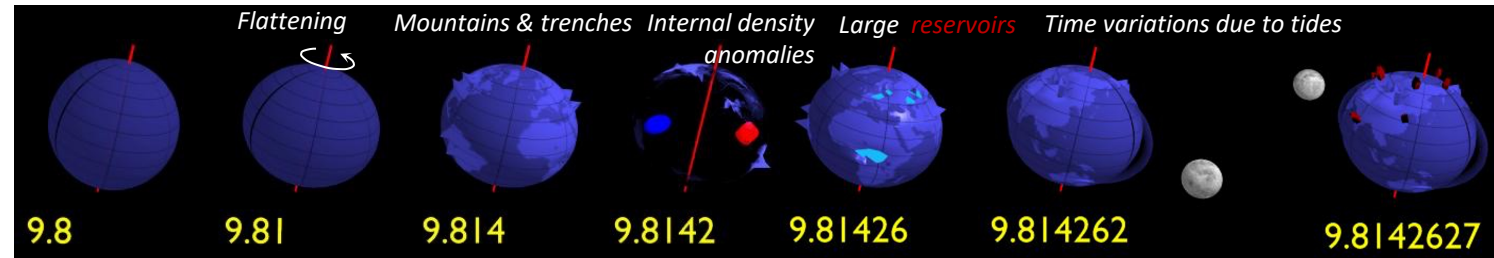
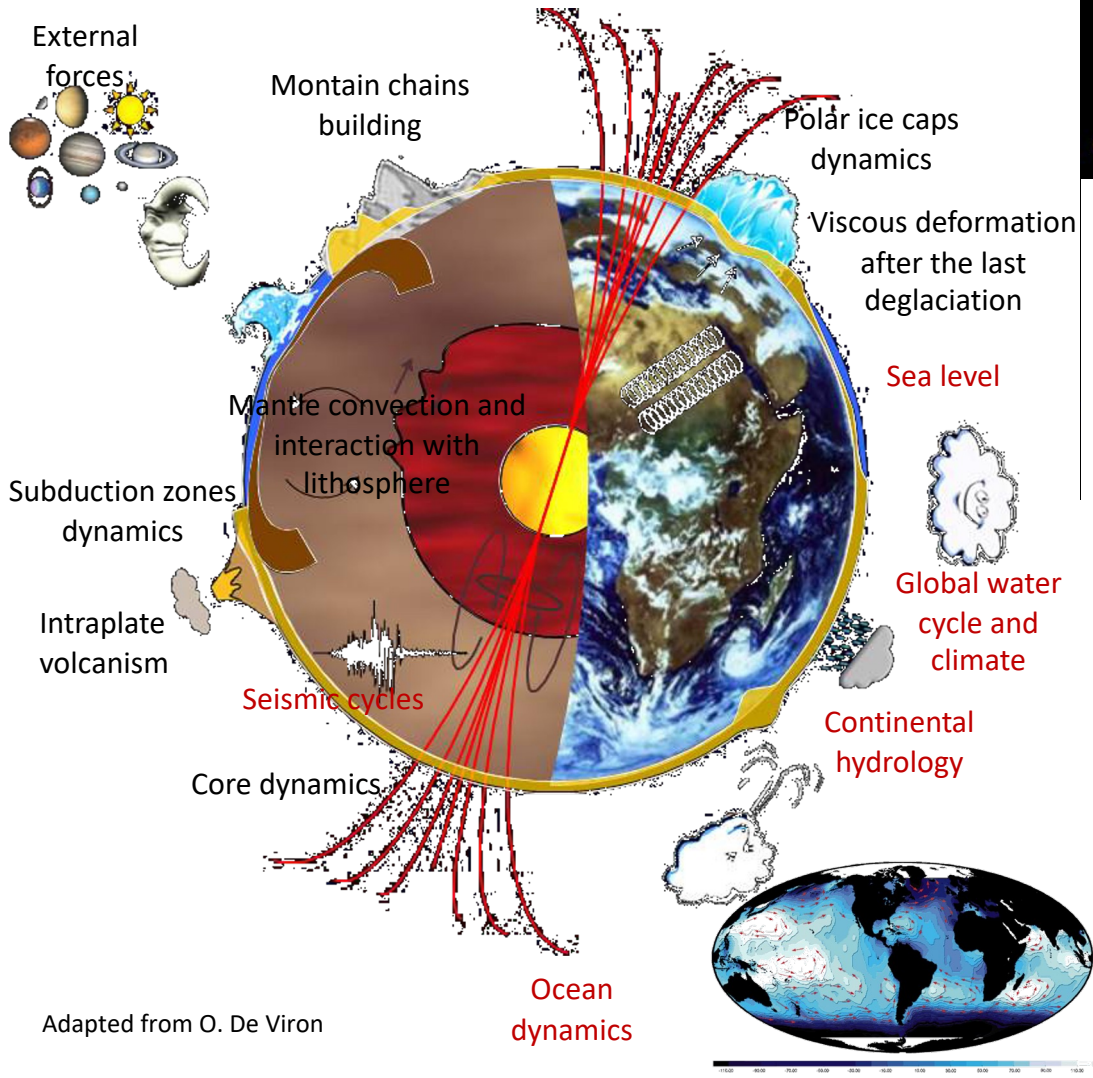
A nearly closed system

- Total mass conserved
- Exchange of energy with the outer space: primarily from solar heating

$$\vec{P} = m\vec{g}$$

Geophysics, Geodesy
... Metrology domain

Earth sciences, gravimetry



Energy, mass, geophysics and gravimetry domain
Needs for references (geoid) and trustables accurate measurements

Needs of Earth references

The United Nation resolution A/RE/69/266 “A Global Geodetic Reference Frame for sustainable development” (<https://undocs.org/en/A/RES/69/266>) calls for the **establishment of an improved Global Geodetic Reference Frame (GGRF)** which is **essential for reliable determination of changes in the Earth system, for natural disaster management, for monitoring sea-level rise and climate change, and for providing accurate informations for decision-makers.**

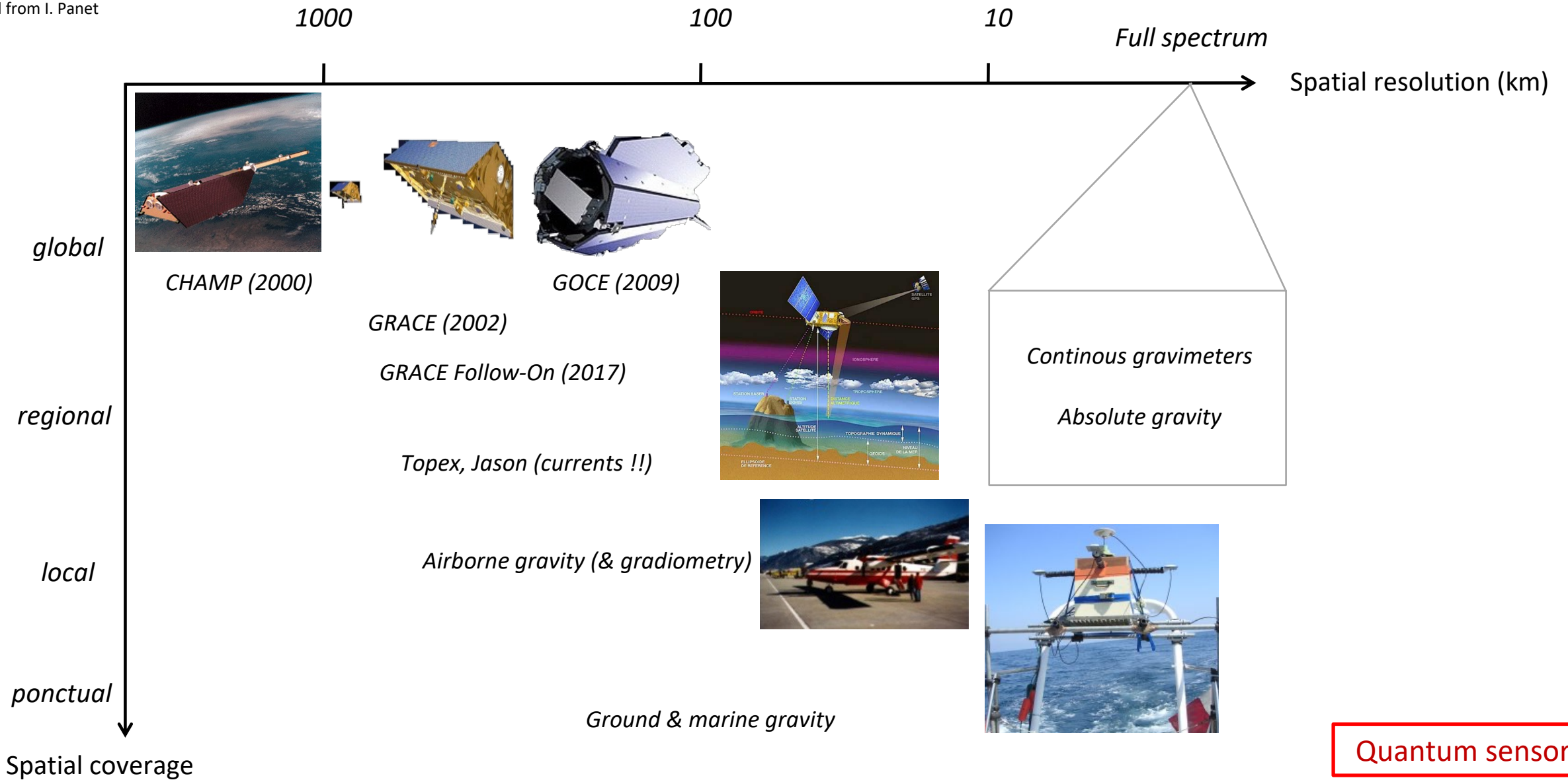
The United Nations proclaimed a Decade of Ocean Science for Sustainable Development, to be held from 2021 to 2030. With the Global Ocean Observing System (GOOS) (<https://www.goosocean.org/>), a program executed by the Intergovernmental Oceanographic Commission (IOC) of the UNESCO, the pursued goals can be summarized as follows : *(i)* assess the cumulative impacts of climate change and *(ii)* observe, understand in order to anticipate, inform and adapt.

Survey of gravity evolution. Science based on long term observations.

Instruments based on quantum technologies offer decisive advantages due to their intrinsic properties: accuracy, SI traceability, stability, which will revolutionize the measurement practices in geodesy.

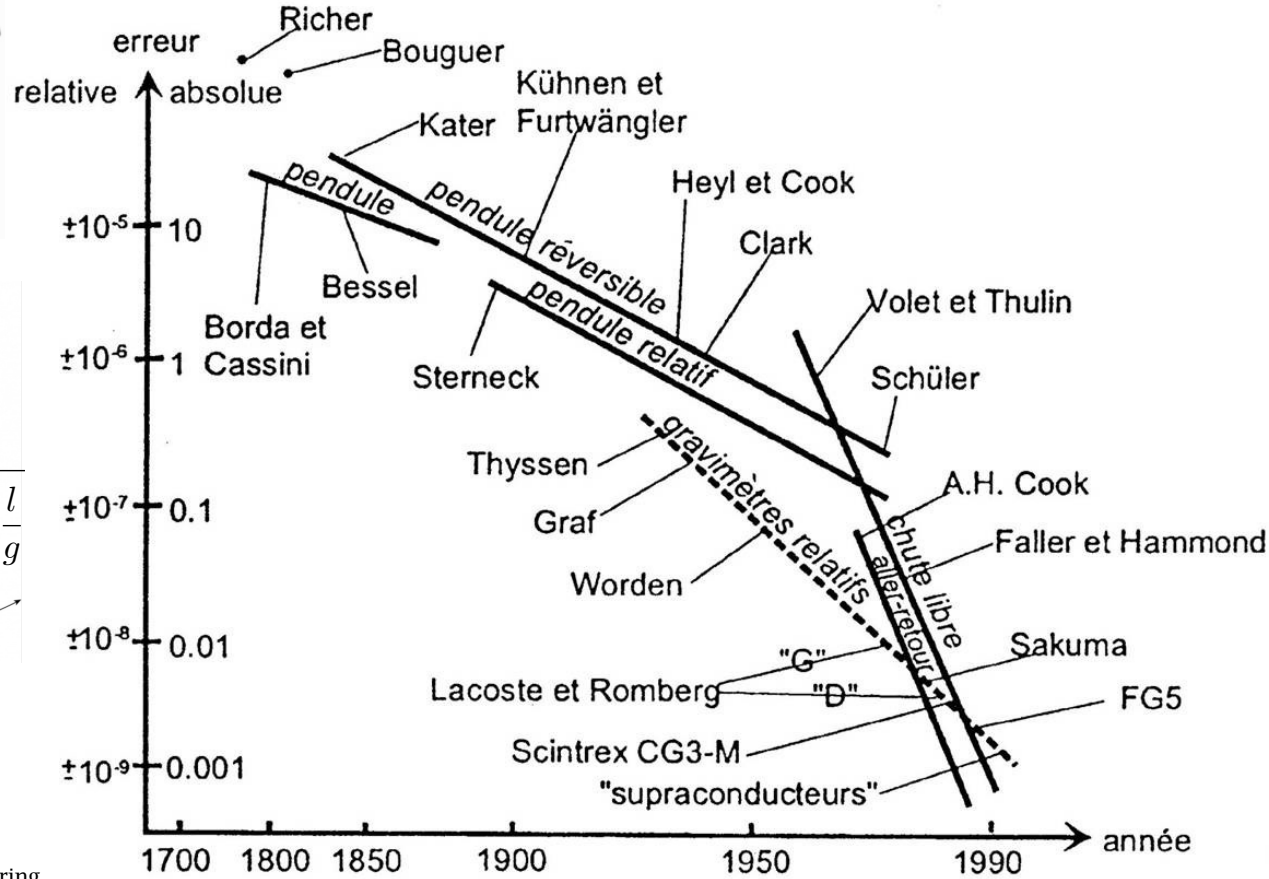
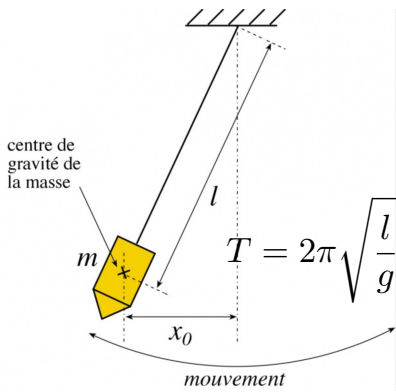
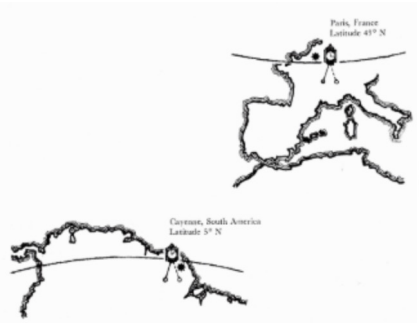
Measurements (up to now)

Adapted from I. Panet

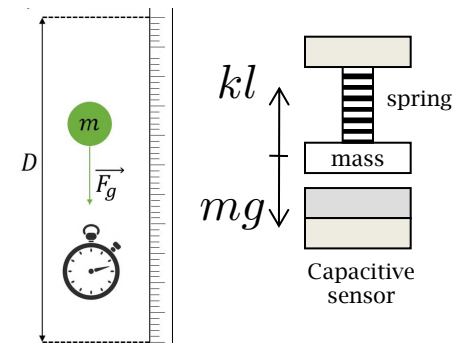


Quantum sensors ?

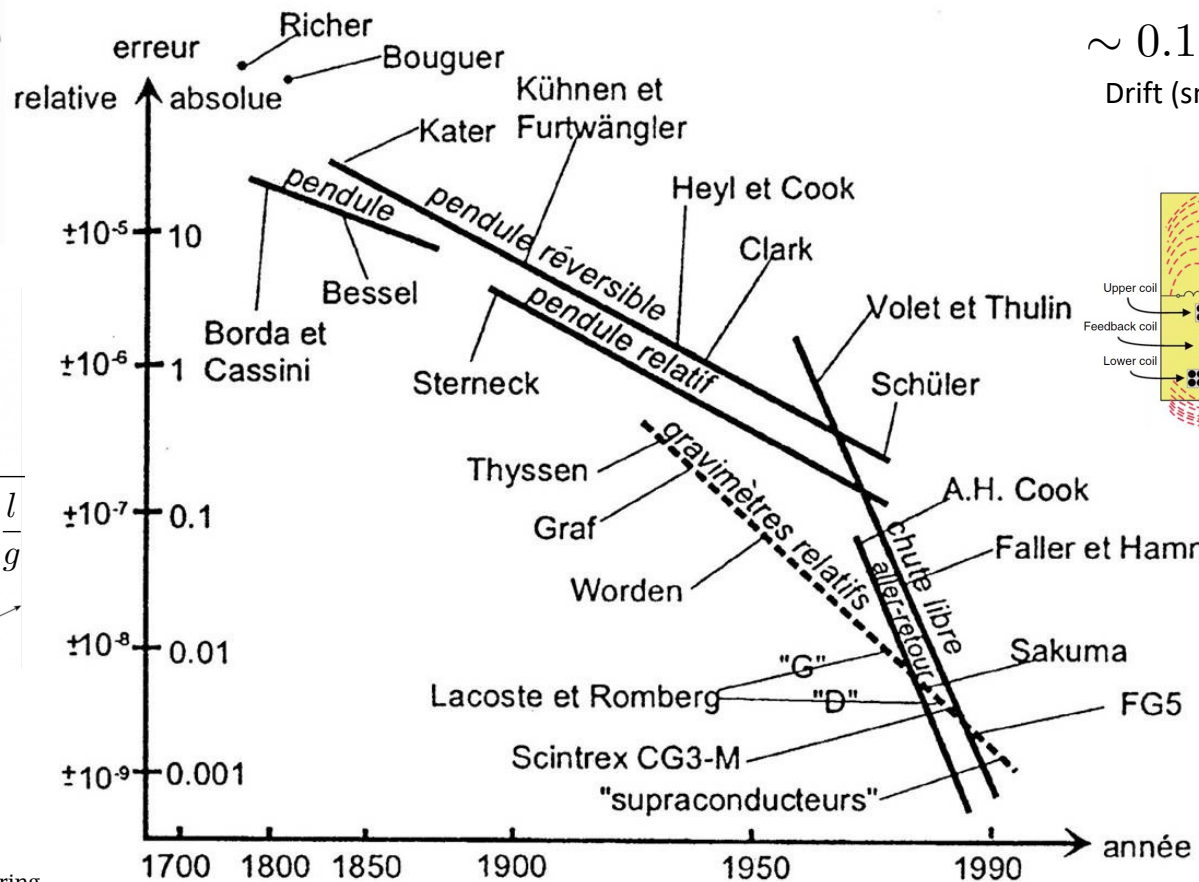
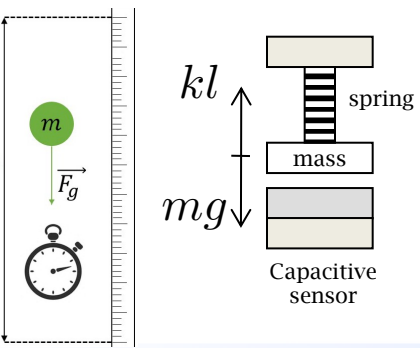
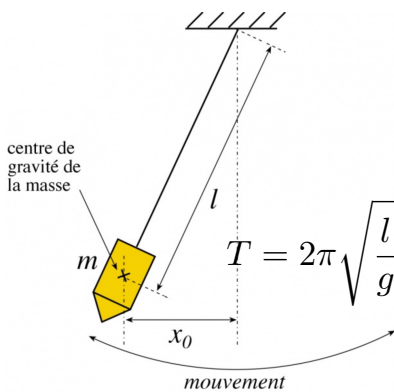
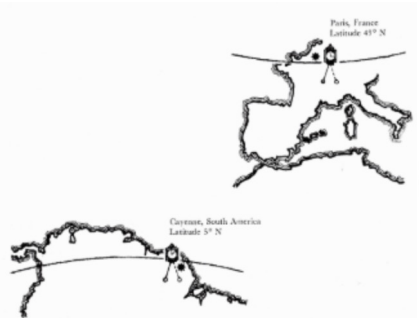
Instruments



Adapted from W. Torge

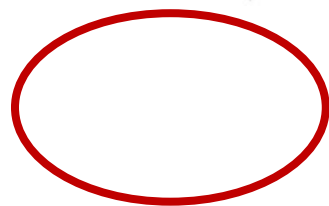
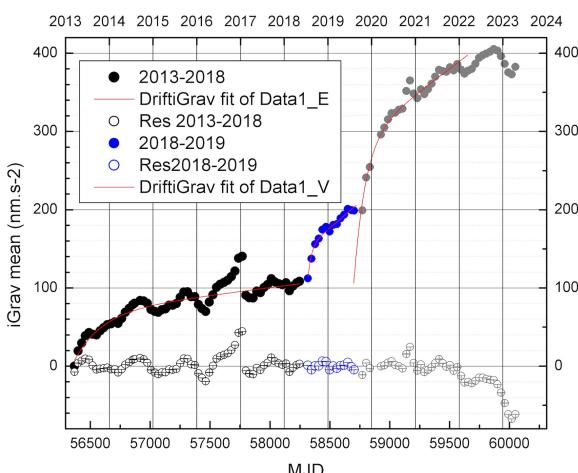
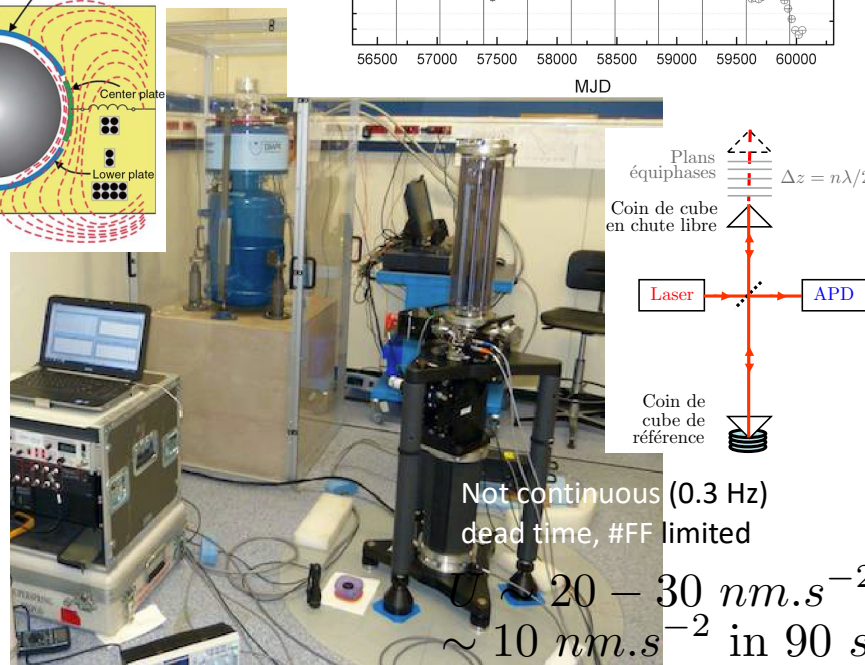
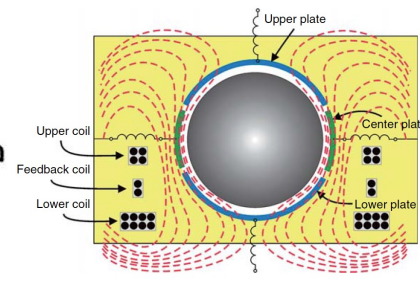


Instruments



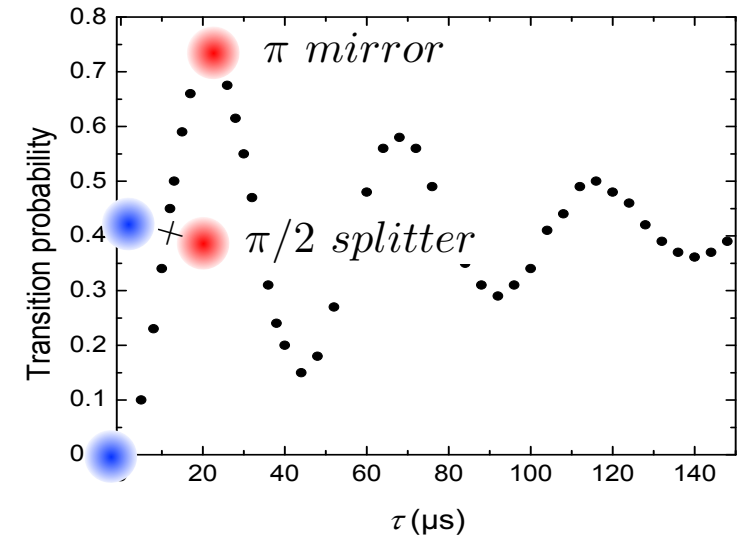
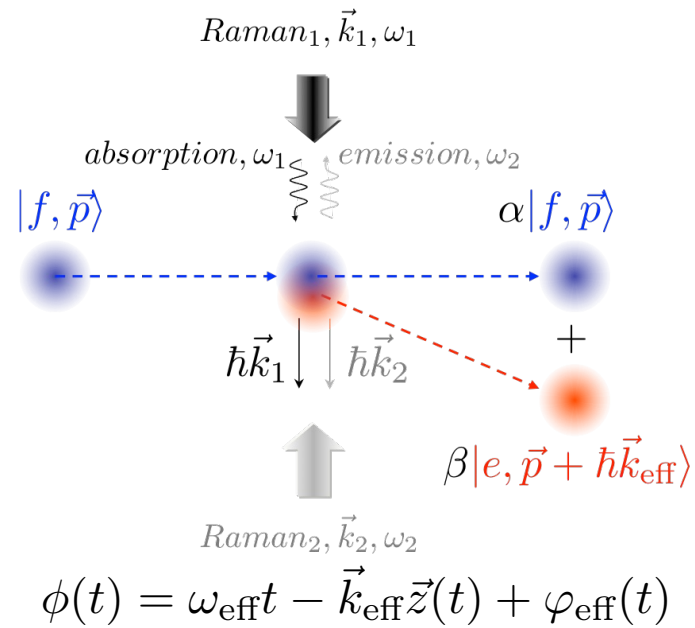
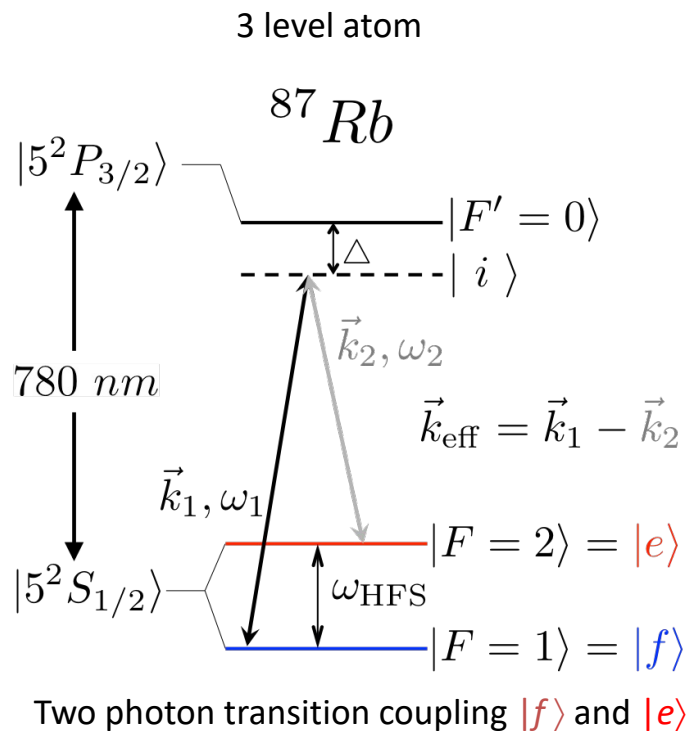
Adapted from W. Torge

Continuous (1 Hz averaged)
 $\sim 0.1 \text{ nm.s}^{-2}$ in 1 000 s
 Drift (small but NL in the 2 first years)
 Not accurate, to be calibrated

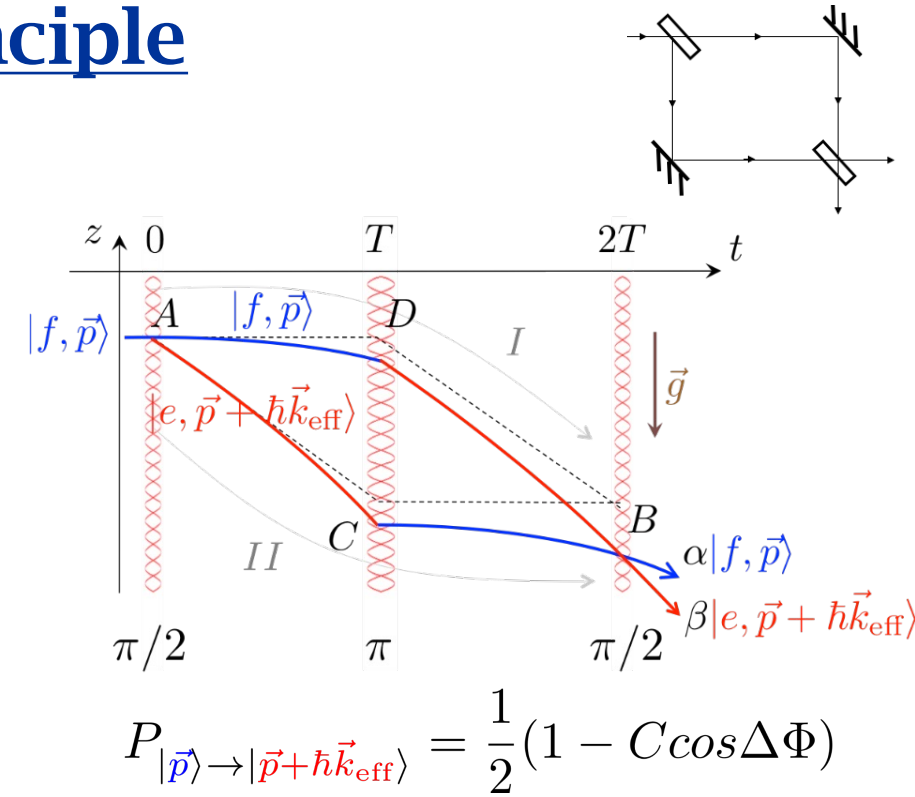
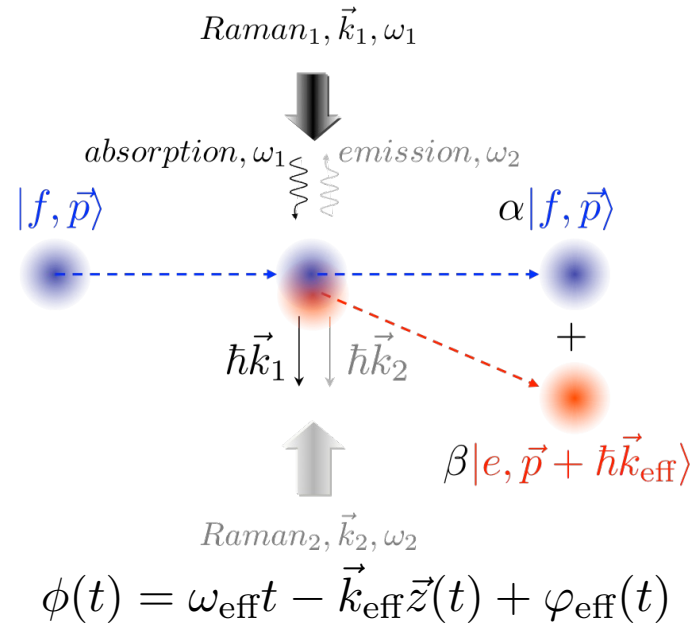
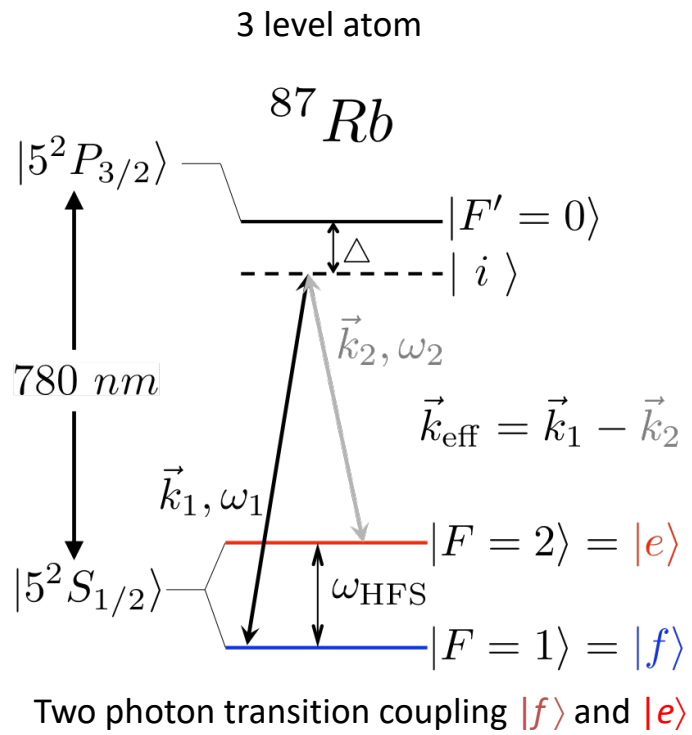


Needs of accurate and continuous sensors, new sensors, new ideas
 Quantum Technologies ?

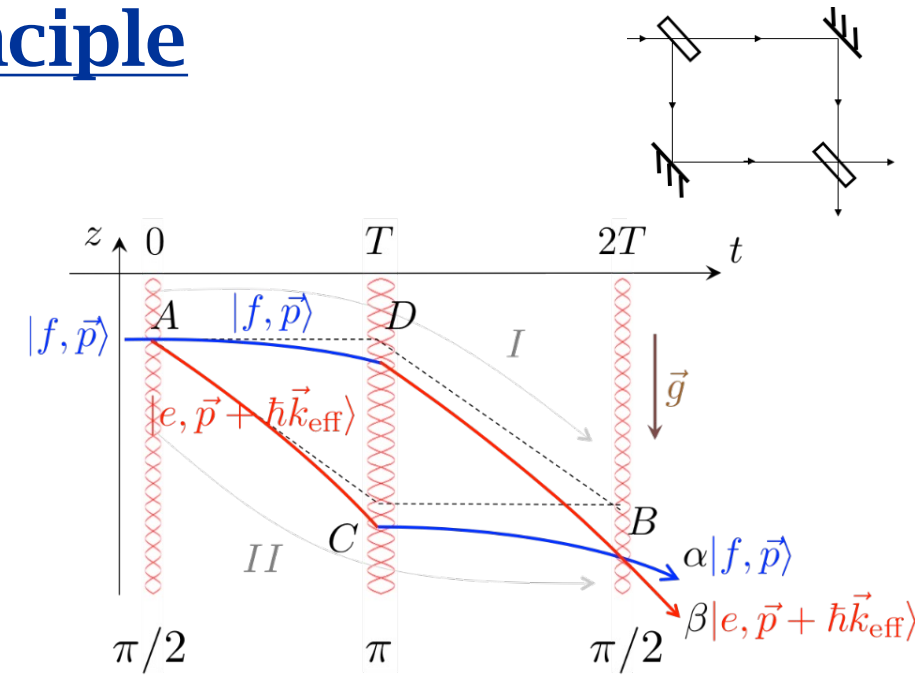
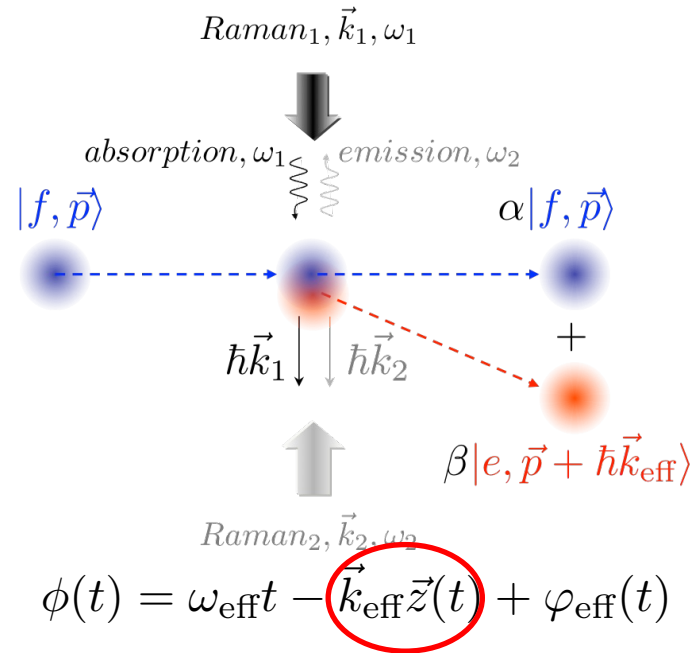
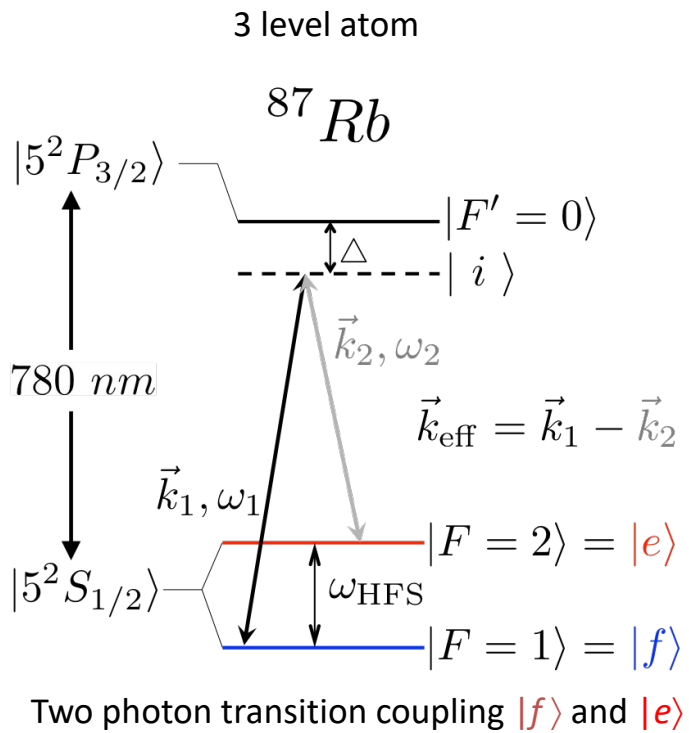
Atom Interferometer, principle



Atom Interferometer, principle



Atom Interferometer, principle



$$P_{|\vec{p}\rangle \rightarrow |\vec{p} + \hbar\vec{k}_{\text{eff}}\rangle} = \frac{1}{2}(1 - C \cos \Delta\Phi)$$

$$\Delta\Phi = \Phi_{II} - \Phi_I$$

$$= (\phi_A - \phi_C) - (\phi_D - \phi_B)$$

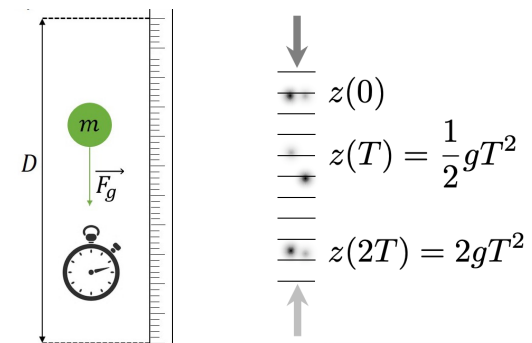
$$= \phi(0) - 2\phi(T) + \phi(2T)$$

$$z = \frac{1}{2}gt^2$$

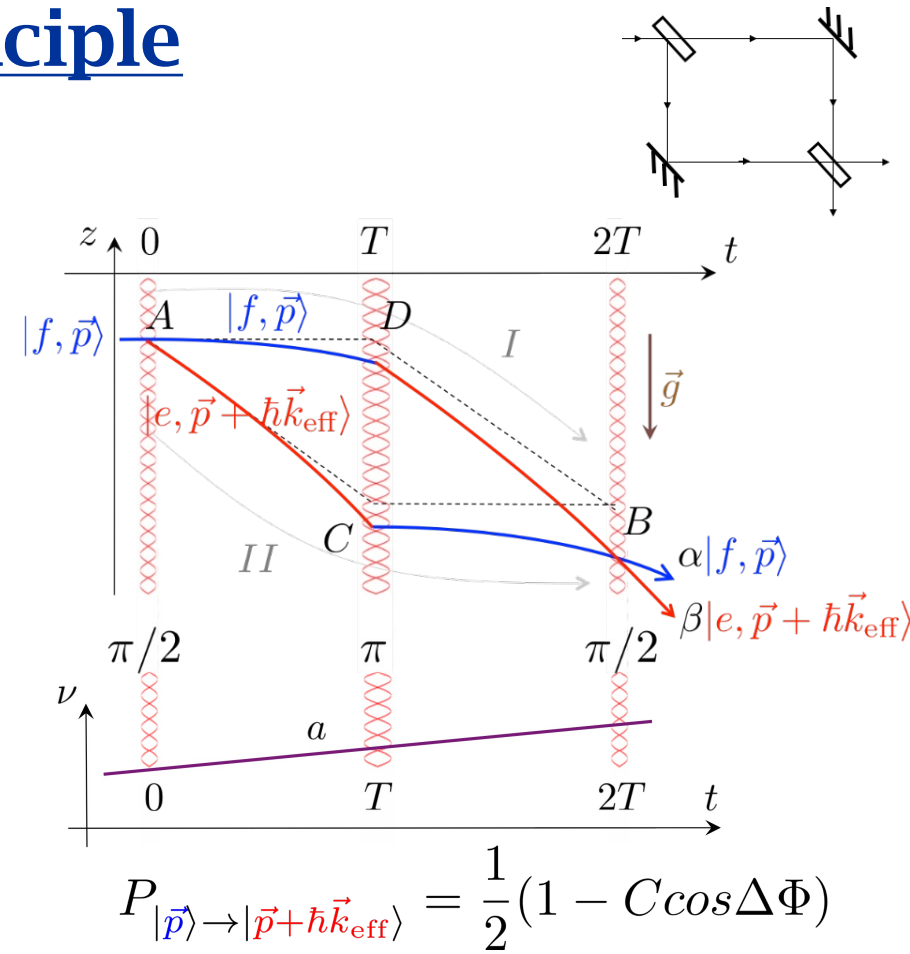
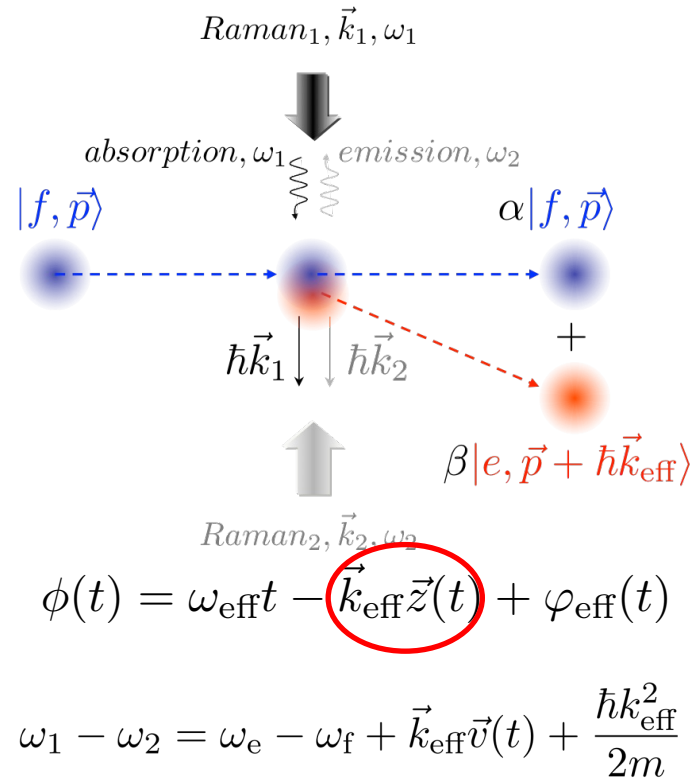
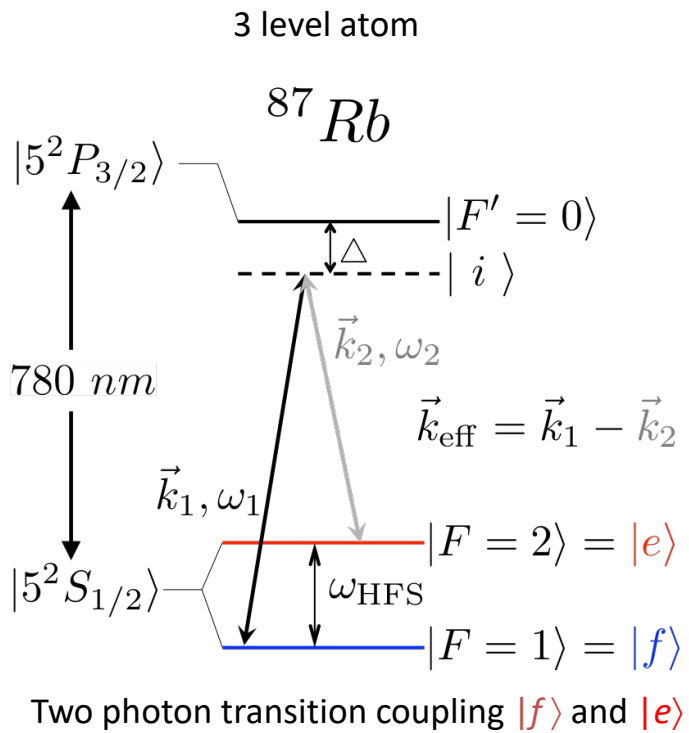
$$\Delta\Phi = -\vec{k}_{\text{eff}}\vec{g}T^2 + \delta\Phi_{\text{noise}} + \delta\Phi_{\text{syst}}$$

Scales as T^2 , benefits of cold atoms

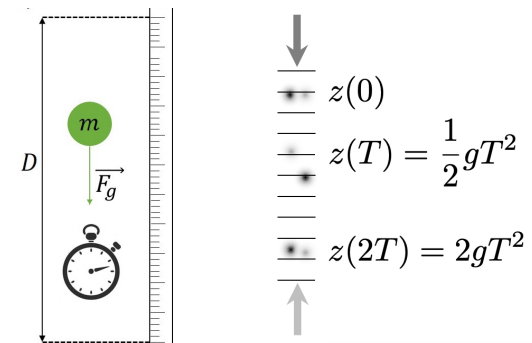
Sampling of the positions at the 3 pulses



Atom Interferometer, principle

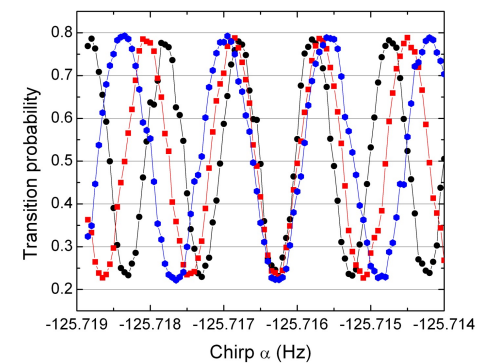


Sampling of the positions at the 3 pulses

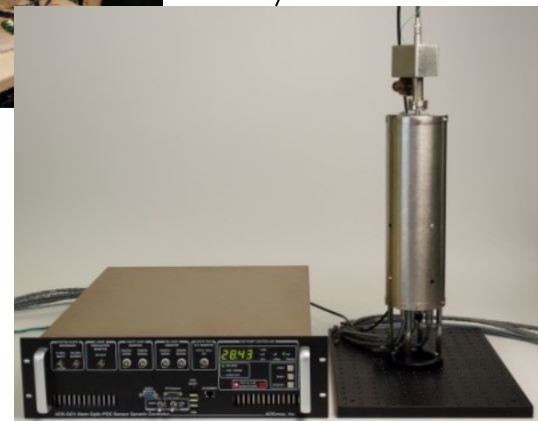
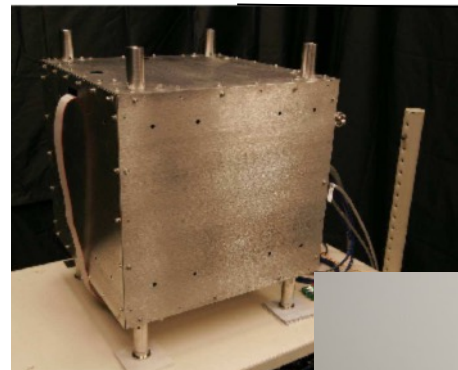
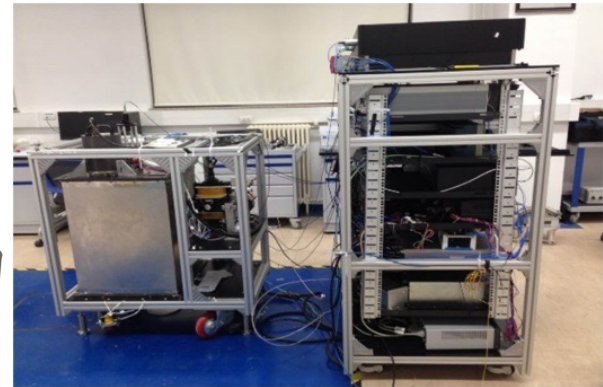
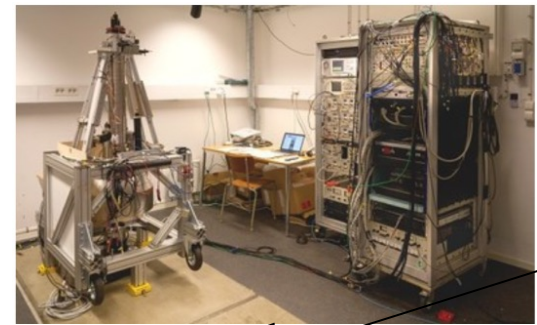
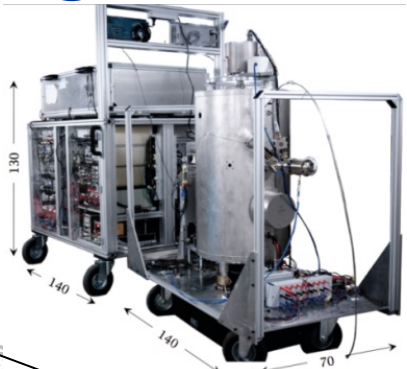
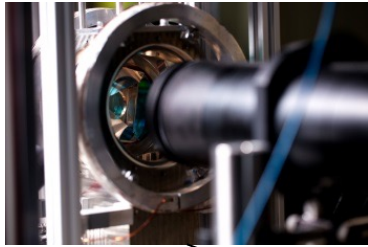
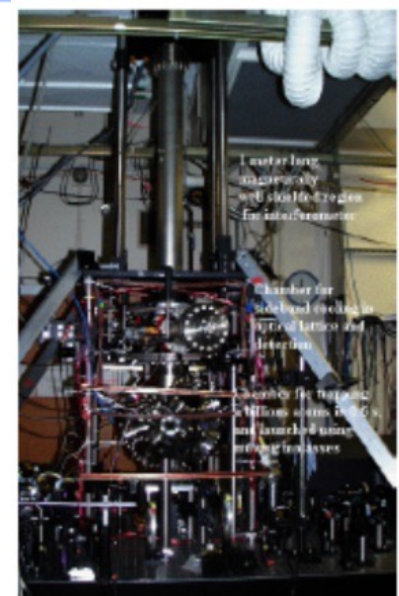


$$\Delta\Phi = -\vec{k}_{\text{eff}}\vec{g}T^2 + aT^2$$

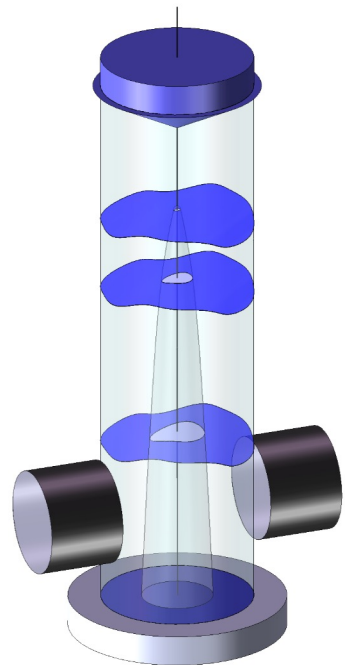
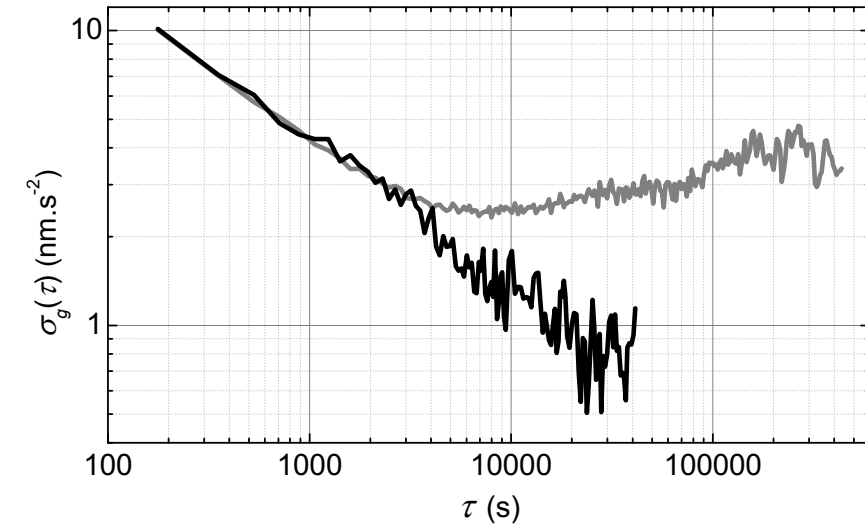
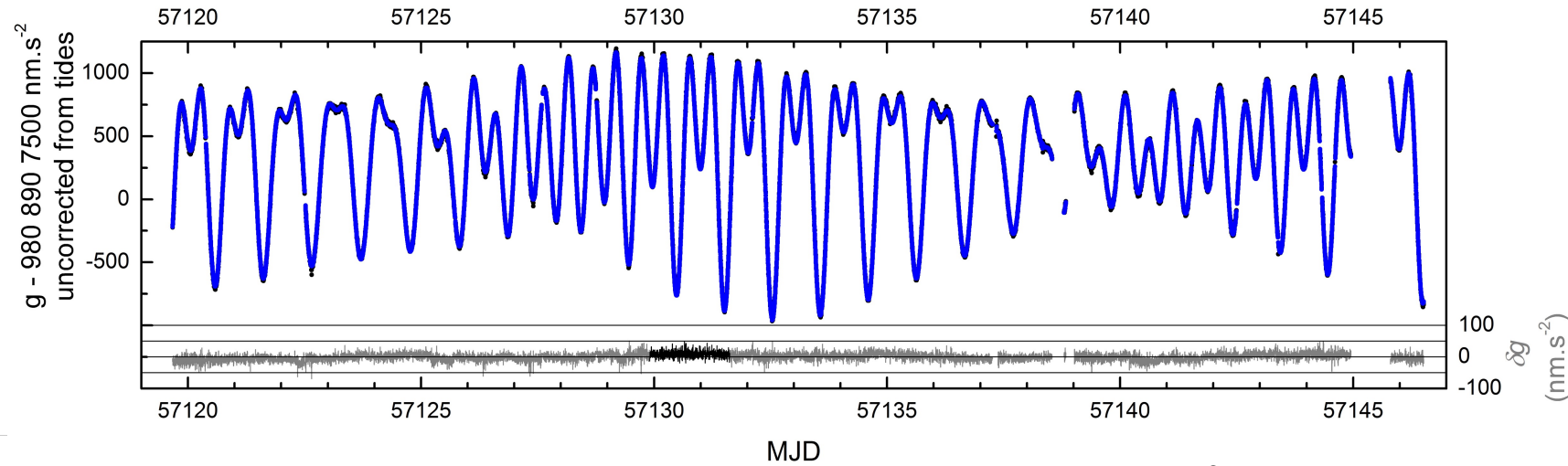
Gravity is a frequency measurement $g = a/k_{\text{eff}}$



Huge worldwide activity

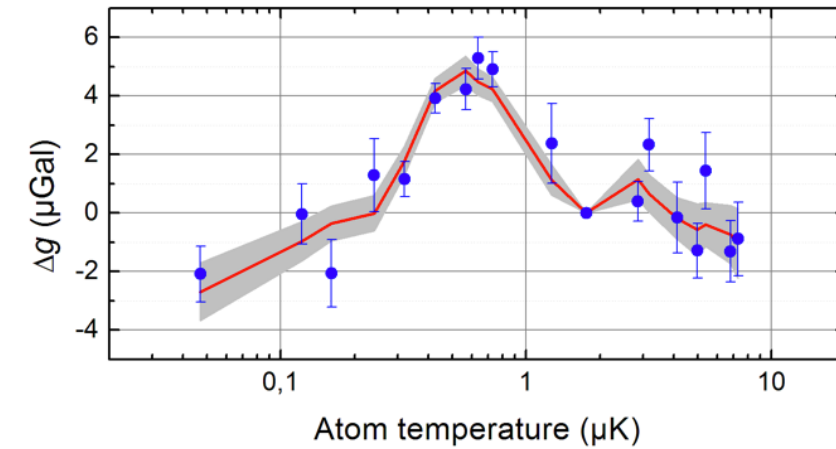
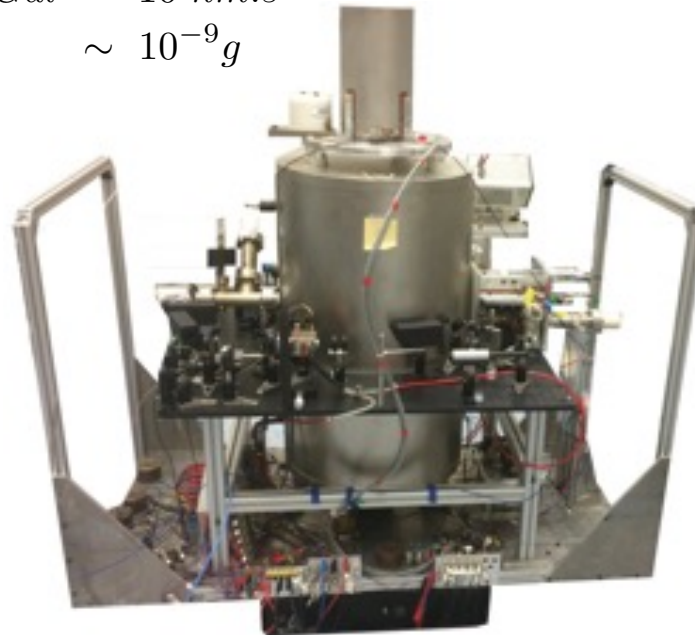


LNE-SYRTE sensor



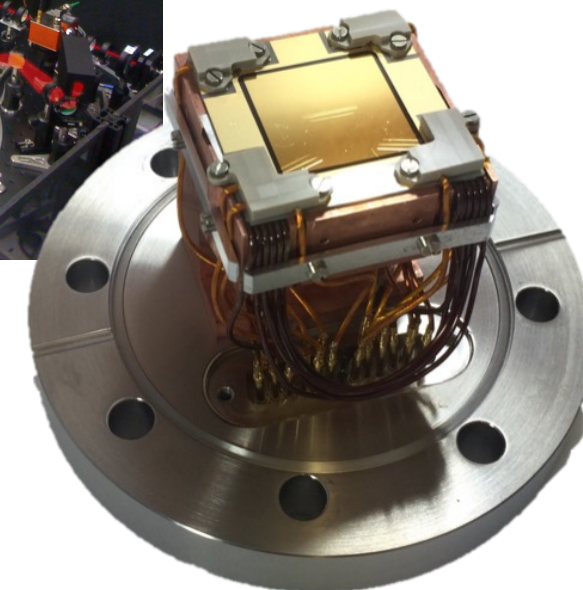
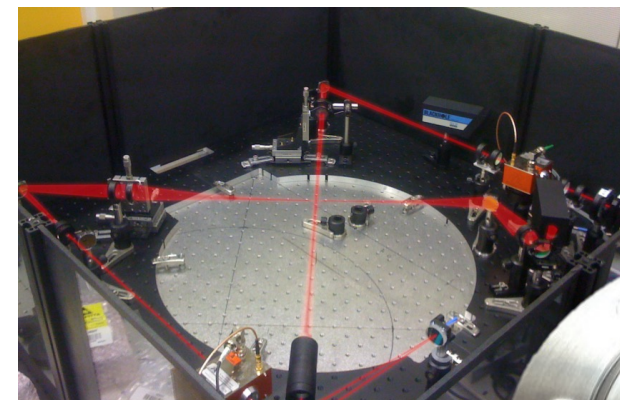
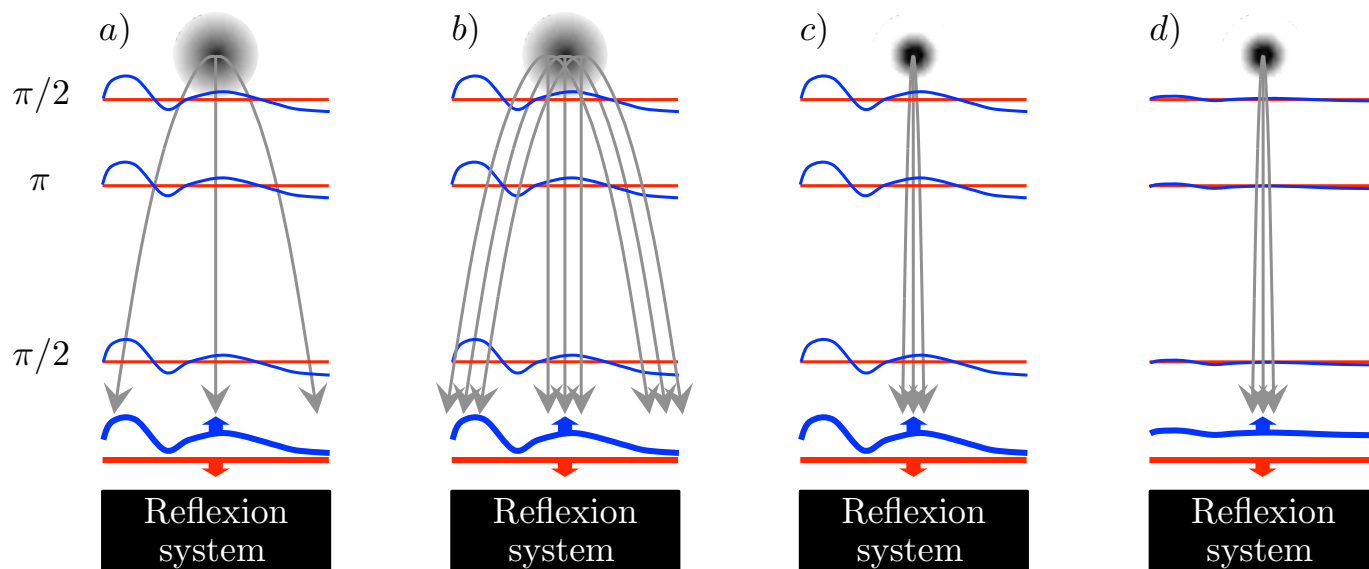
Effect	Bias μGal	u μGal
Alignments	0.3	0.5
Frequency reference	0.5	<0.1
RF phase shift	0.0	<0.1
vgg	-13.4	<0.1
Self gravity effect	-2.1	0.1
Coriolis	-5.3	0.8
Wavefront aberrations	-5.6	1.3
LS1	0.0	<0.1
Zeeman	0.0	<0.1
LS2	-3.6	0.8
Detection offset	0.0	0.5
Optical power	0.0	0.5
Cloud indice	0.4	<0.1
Cold collisions	<0.1	<0.1
CPT	0.0	<0.1
Raman α LS	0.3	<0.1
Finite Speed of Light	0.0	<0.1
TOTAL	-28.5	2.0

$1 \mu\text{Gal} = 10 \text{ nm.s}^{-2}$
 $\sim 10^{-9} g$



Several teams at similar level
 Comparison needed. How to go further ?

Evolution, improvement



From cold (μK) to ultra-cold (nK) atomic source : optical or magnetic trap (fast)

→ Metrological tool to investigate wavefront bias : accuracy

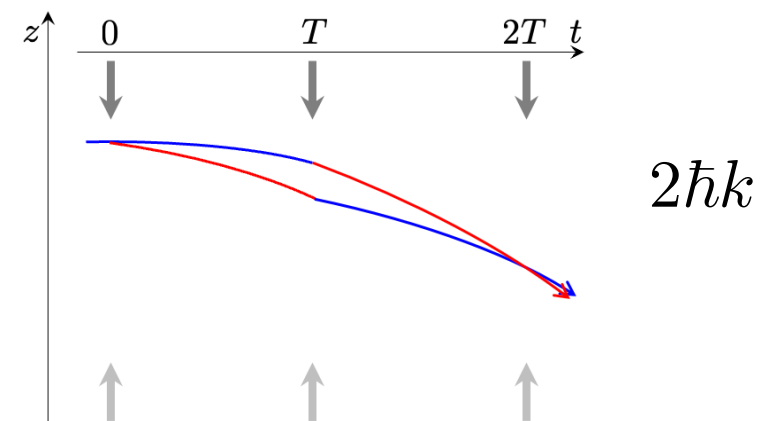
→ Stabilize the atom source point : long term sensitivity

From 2 to $2 \times N$ photon transitions : LMT, Bragg
(and T)

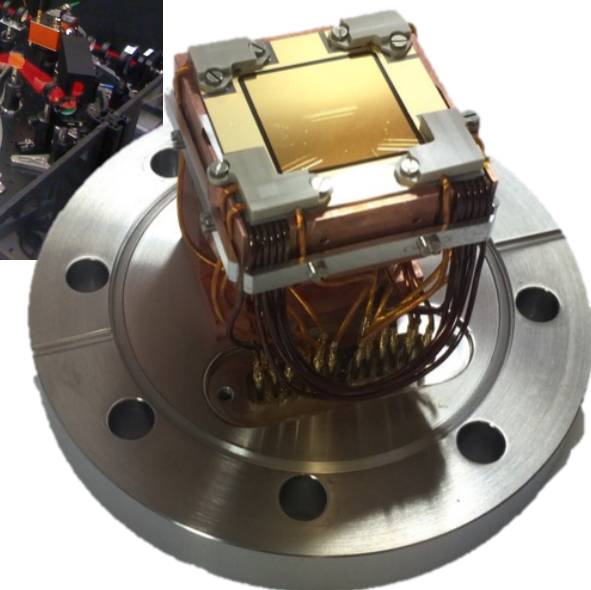
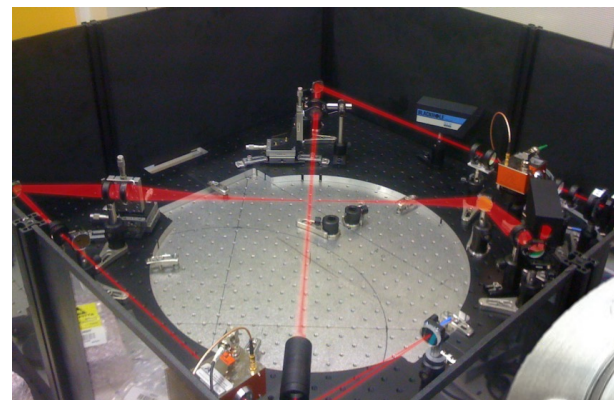
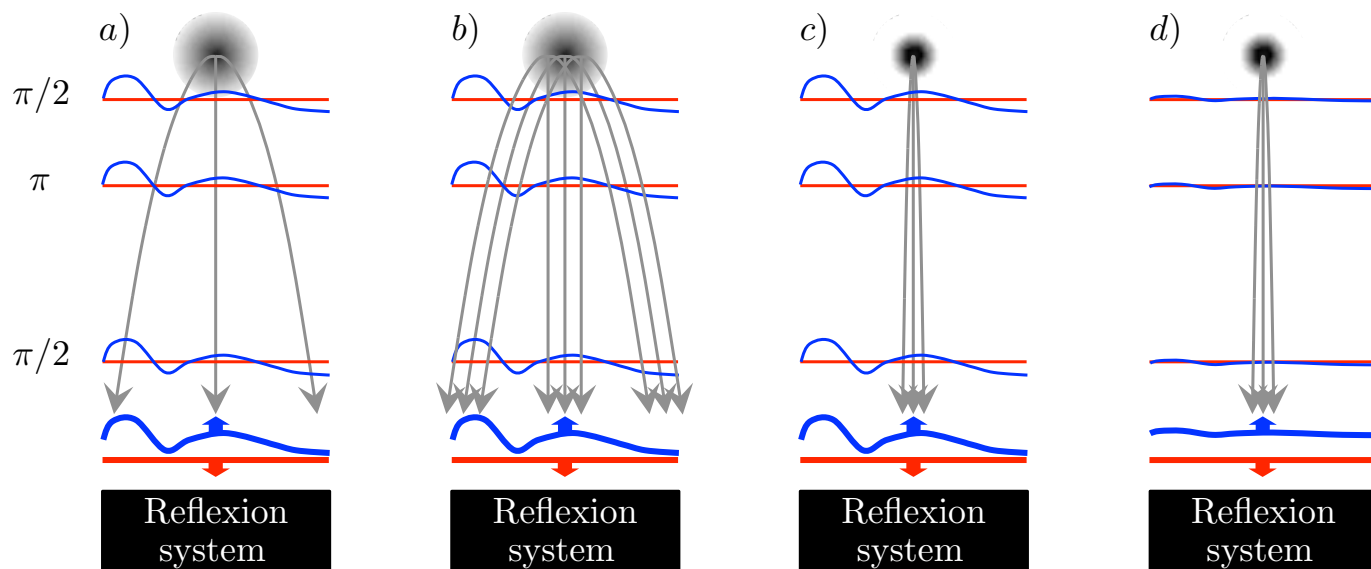
→ Improve the scale factor, so sensitivity

$$\Delta\Phi = \vec{k}_{\text{eff}} \vec{g} T^2$$

↑ ↑



Evolution, improvement



From cold (μK) to ultra-cold (nK) atomic source : optical or magnetic trap (fast)

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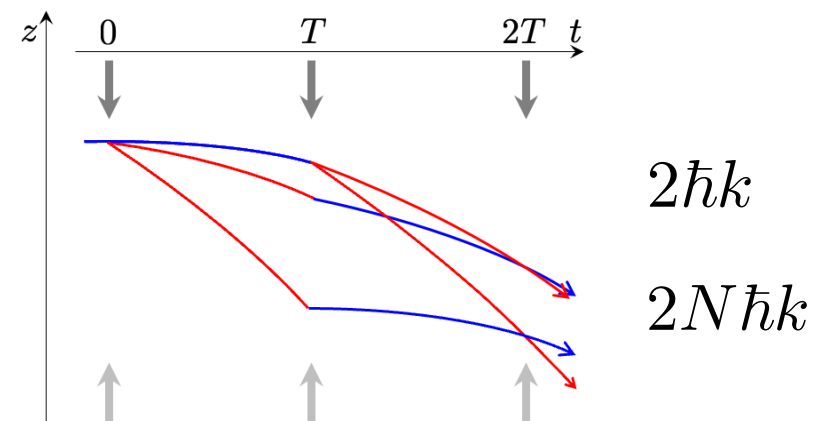
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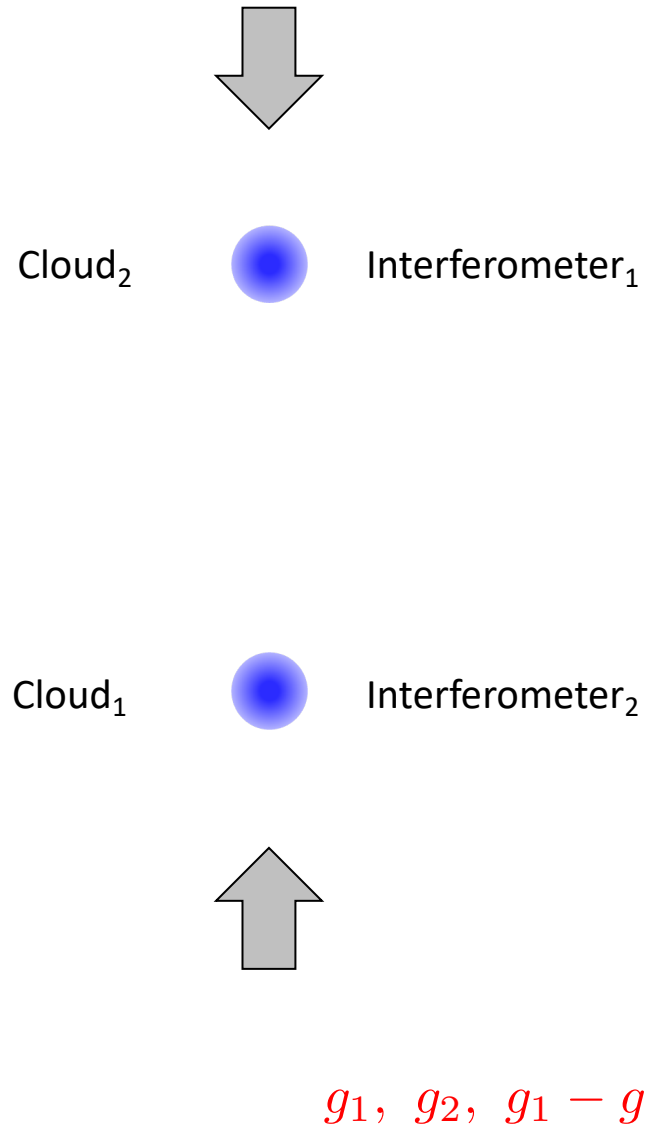
→ Improve the scale factor, so sensitivity

$$\Delta\Phi = \vec{k}_{\text{eff}} \vec{g} T^2$$

↑ ↑



New sensors, with improvements



- **Simultaneous** interferometers on two cold atom clouds with **common lasers**
- **Differential measurement** allows for extracting the **acceleration difference** (and thus the **Earth gravity gradient**)
- **Suppression of common mode noise**, and in particular of the vibration noise
- Adapted for onboard measurements
- g and Δg : **resolve ambiguities** in determination of mass and position

With the new tools

- High order Bragg diffraction LMBS with up to N photons
- Ultracold atoms
Fast generation on atom chip

Quantum dual gravi-gradio meter

- 2 ultracold Rb clouds obtained on 2 chips
- 2 clouds launched with elevator
- 2 Interferometers driven by LMTB

Targeted parameters

$$T_c = 2s \quad N_{\text{atoms}} = 5 \cdot 10^5$$

$$T_{\text{emp}} = 10 - 100nK$$

$$p = 100\hbar k \quad 2T = 0.5s$$

$$\sigma_g^1 = 9 \times 10^{-11} m \cdot s^{-2} \cdot Hz^{-1/2}$$

If limited by QNP

$$\Delta z = 1m$$

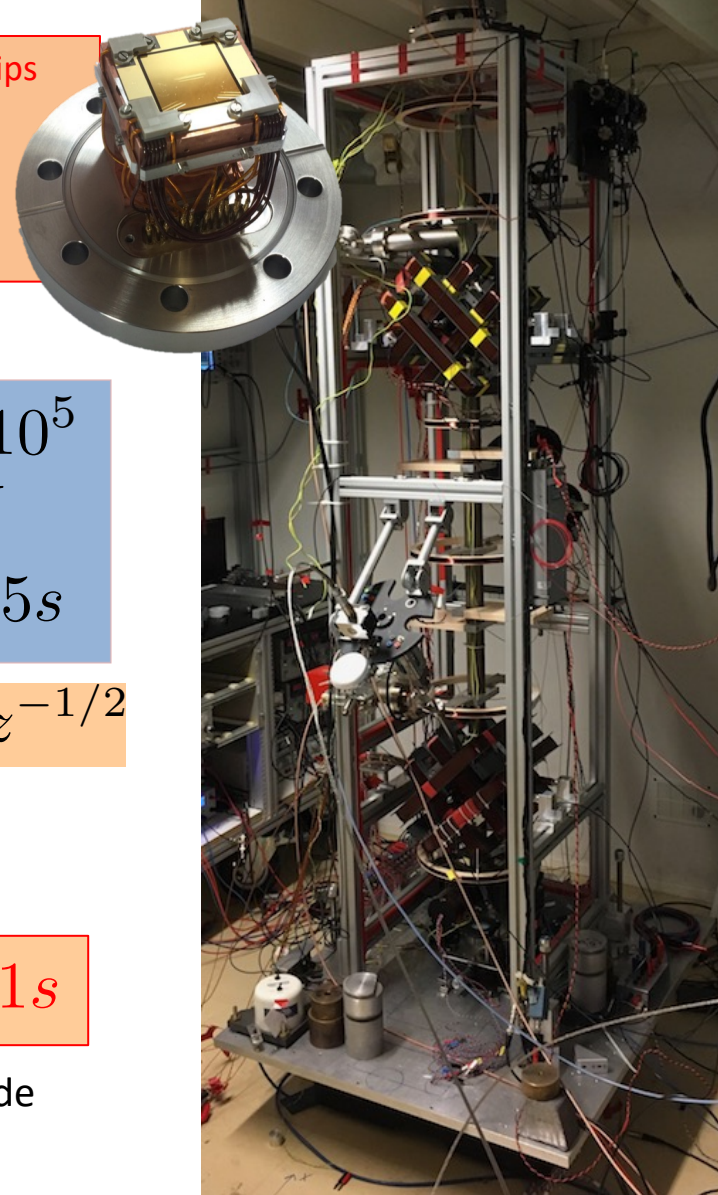
$$\sigma_{\text{grad}g} = 126 mE @1s$$

More than one order of magnitude
better than state of the art

$$1 E = 10^{-9} s^{-2} = 0.1 \mu Gal \cdot m^{-1}$$

R. Caldani et al., Phys. Rev. A 99 033601 (2019)

WS CCM – BIPM - 2023



Method of dual measurement
transferred in frame of a
collaboration.

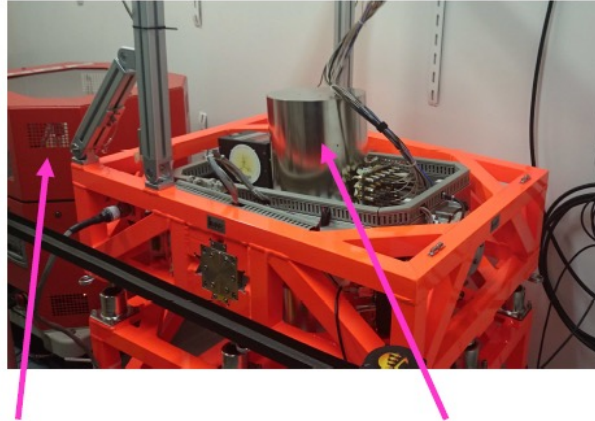
*C. Janvier et al., Phys. Rev. A
105 022801 (2022)*



exail

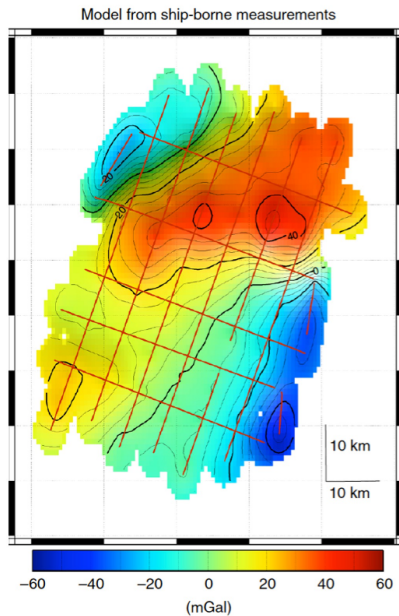
Mobile sensors : more than transportable, onboard measurements

ONERA compact gravimeter for marine gravimetry cartography



Y. Bidel et al Nat Commun. 9, 627 (2018)

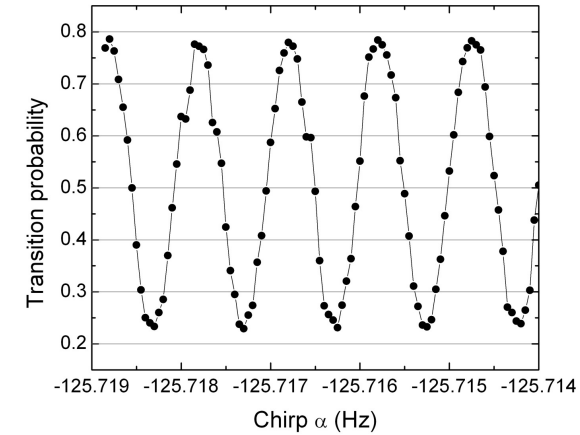
KSS32 relative Marine Gravimeter (Bodenseewerk) Cold Atom Gravimeter (Onera)



With a gyrostabilised platform. Better performance of Girafe2 absolute sensor: suppression of errors due to initial calibration and drift of relative sensor. **Gain : factor 2-3**

+ flying campaign

Y. Bidel et al J. Geod. 94, 20 (2020)



ADEQUADE (Advanced, Disruptive and Emerging QUAntum technologies for Defense) European Defence Fund lead by THALES with ONERA

Strap down sensor: so franges problem, atom in the beam ? control optimal, tip tilt, top hat

Going farer ? Space

Space

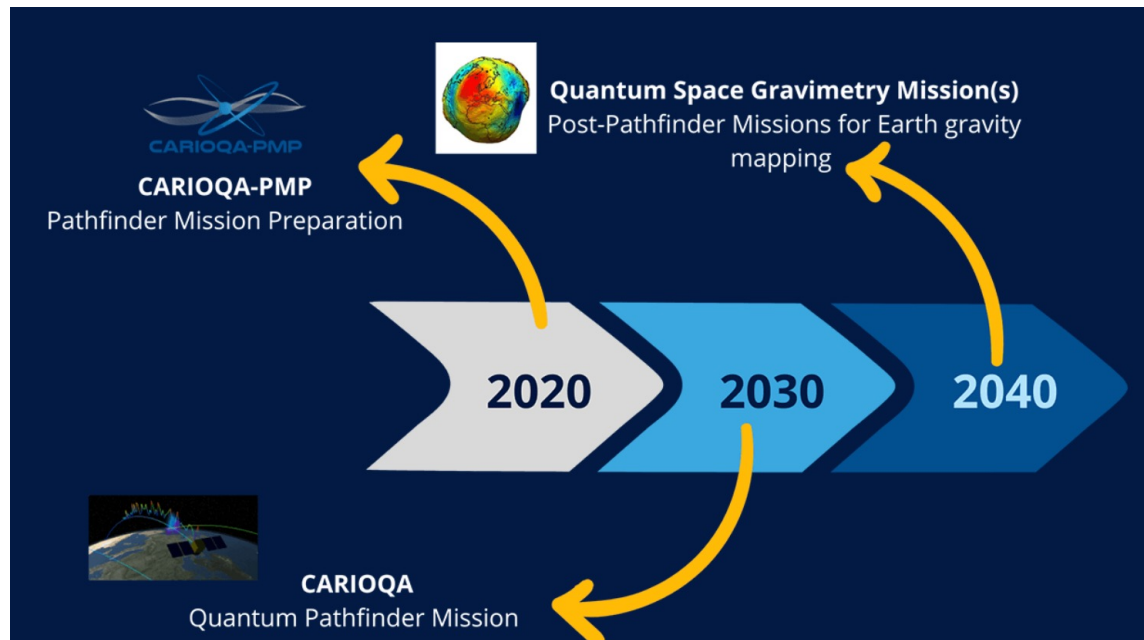
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CARIOQA-PMP: Towards climate studies using quantum technologies

Learn more

Cold Atom Rubidium Interferometer in Orbit for Quantum Accelerometry



<https://carioqa-quantumpathfinder.eu>

<https://quge.iag-aig.org>

International Association of Geodesy
Novel Sensors and Quantum Technology for Geodesy

QUANTUM GEODESY IAG LINKS

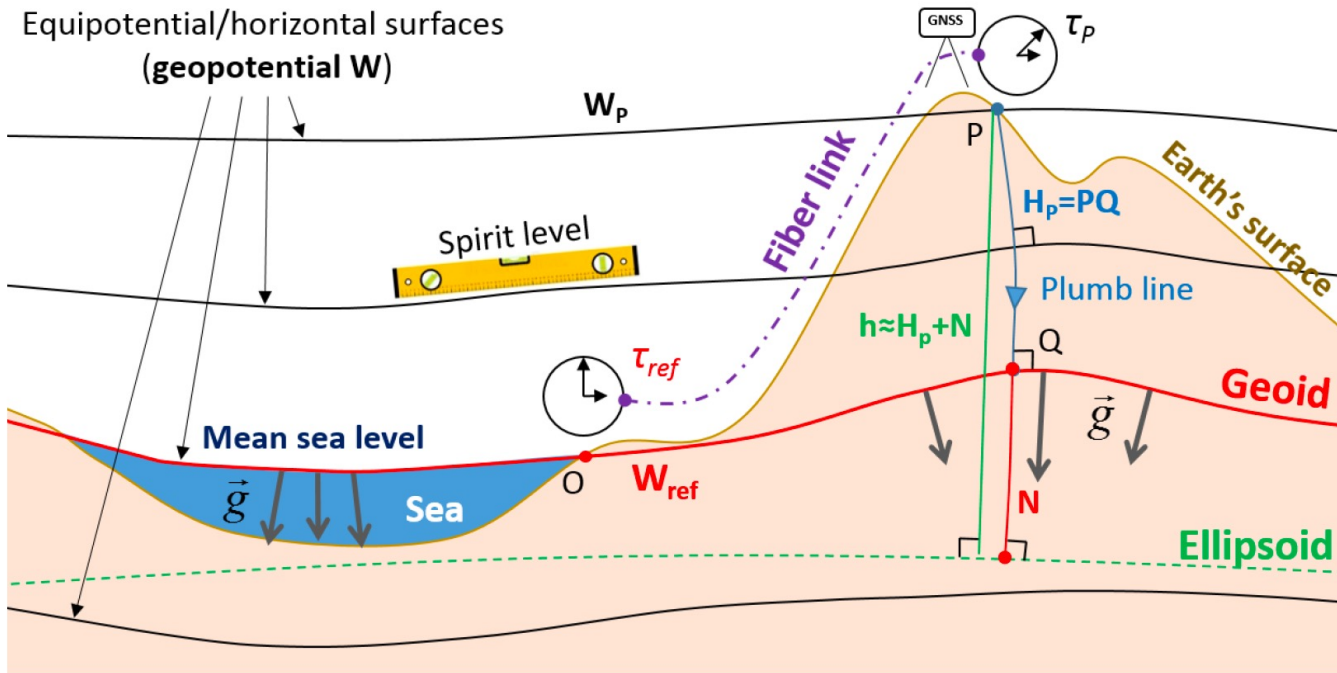
IAG Project - Novel Sensors and Quantum Technology for Geodesy

WG Q.1: Quantum gravimetry in space and on ground

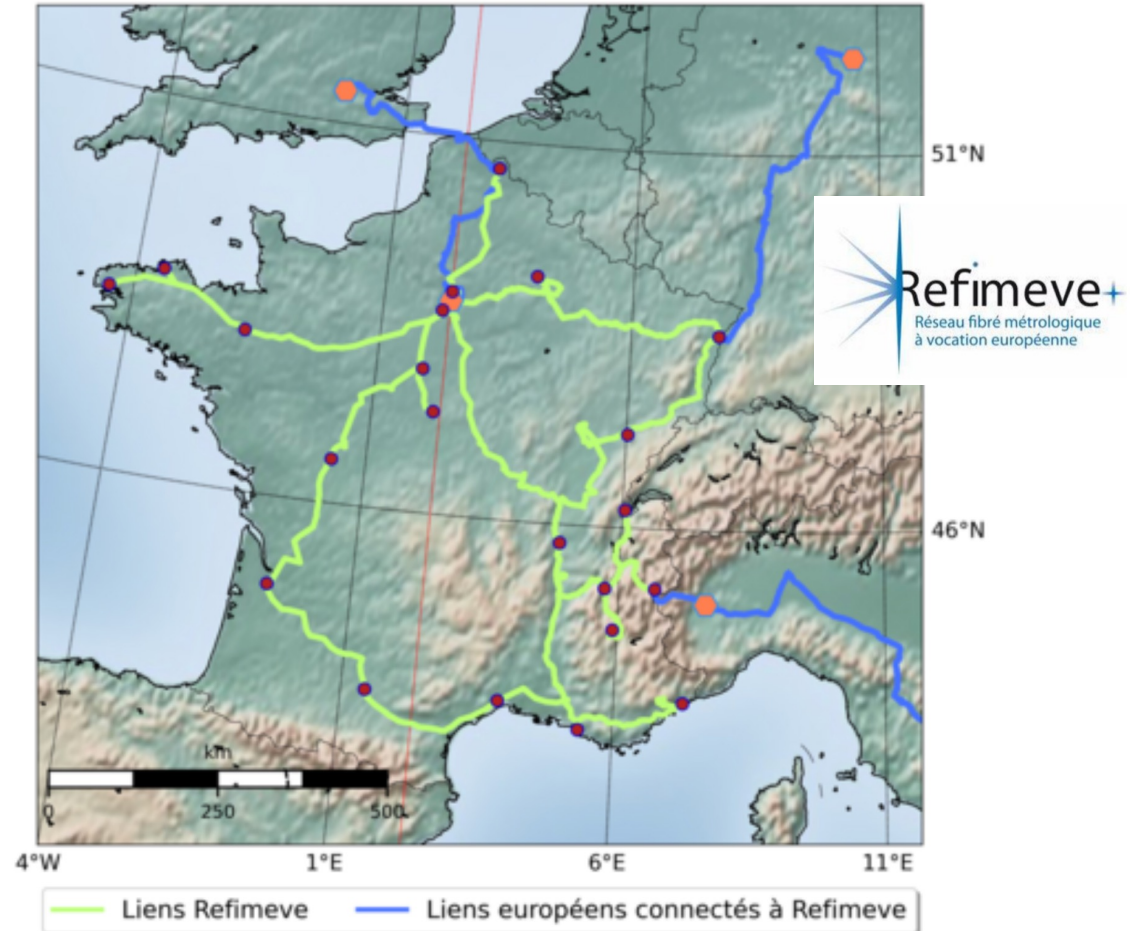
WG Q.2: Laser interferometry for gravity missions

WG Q.3: Relativistic geodesy with clocks

Clocks

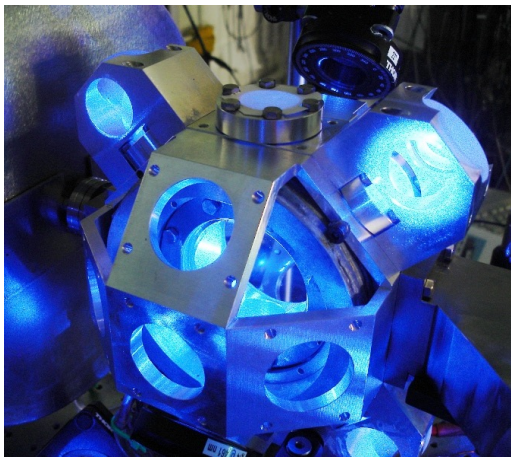


<https://www.refimeve.fr>



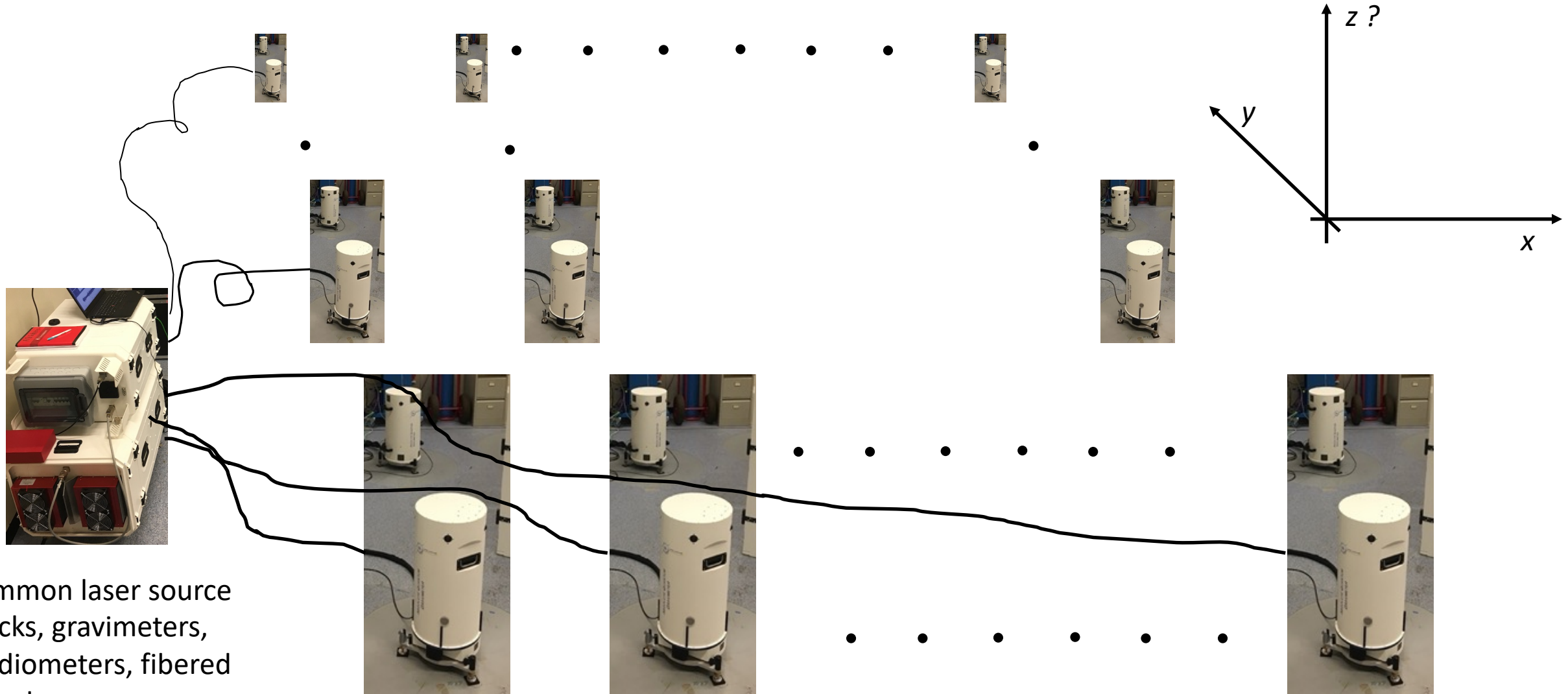
Why not using this network to, not only connect clocks, but also gravi-radio-meters ? Altogether.

$1\text{cm} \rightarrow 10^{-18}$



Fixed lab clocks
Movable clocks

Arrays



Common laser source
Clocks, gravimeters,
gradiometers, fibered
linked

Conclusion

Atomic sensors (gravimeters, gradiometers, dual gravi-gradiometers, gyroscopes, clocks, arrays of quantic sensors) are promising devices to establish references.

Because they are metrologically studied, absolute, no drift, limits not identified.

All scales, from ponctual to space, we will need nodes stations for continuous measurements, and satellites for global ones.

Need of several sensors at top level, in agreement, metrological.

Many countries involved. Many domain involved.

Industrial transferts (fiabilisation, automatisation).

*Establishing and maintaining a long term geodetic reference system is of key importance for **climate monitoring and Earth observation systems**. This long standing objective of the geoscience community is well supported by relevant international organisations. The need of better monitoring of **critical parameters, such as ocean level, demands an improved accuracy of the global reference system down to the mm level, which constitutes the challenge to meet to evaluate accurately the cumulative impact of climate changes.***

State of the art

$$1 \mu\text{Gal} = 10 \text{ nm.s}^{-2} \sim 10^{-9} g$$

Type	Techno	Institut / Company	Name	ν_c Hz	u μGal	u _{wfab} μGal	σ_g μGal	τ s	Rq
Abs	FFCC	Micro-g Lacoste	FG5X	0.3 0.1	2.0 .	. .	\sim 1.0 1.0	\sim 100 \sim 700	dead time, wearing
Rel	Supra	GWR	iGrav	1.0	.	.	0.01	600	drift
Abs	Atom	SYRTE	CAG	2.8	2.0 . .	1.3 . .	5.7 1.0 0.06	1 36 20 000	T=80ms dropped atoms
Abs	Atom	HUB	GAIN	0.7	3.2 . .	2.2 . .	9.6 1.0 0.05	1 100 100 000	T=260ms launched atoms
Abs	Atom	HUST		0.5	5.0	4.2 1.0 0.3	1 18 200	T=300ms launched atoms
Abs	Atom	muquans	AQG		59.4 1.0 0.3	1 4000 200 000	dropped atoms
Abs	Atom	AOSense				
Abs	Atom	M Squared				

$$\Delta\Phi = -\vec{k}_{\text{eff}}\vec{g}T^2$$

2T difference, not correlated with better performances

Motivation for the development of compact gravimeters (2T \approx 100 ms, h \approx 5 cm)