



# Status Report of the IGS Clock Products

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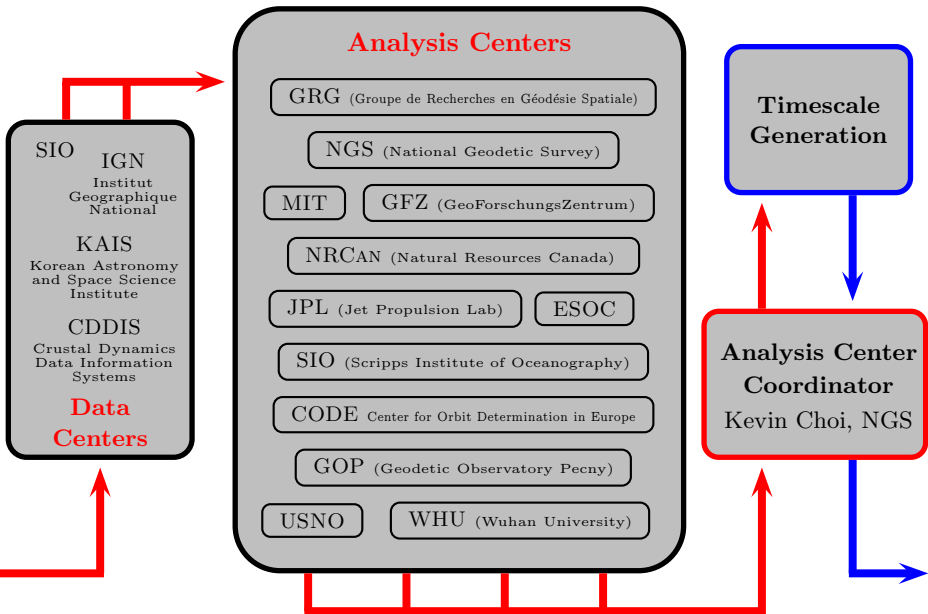
Consultative Committee  
on Time and Frequency  
*Bureau International  
des Poids et Mesures  
Sèvres, Cedex, France*

## Existing IGS Core Products

SERIES	Product	Interval	Accuracy	Issue Time	Latency
ULTRA RAPID (IGU)	GPS ORBITS	15 MIN	~ 3.0 cm	Daily at 03:00 09:00 15:00 21:00 UTC	3 – 9 Hours
	GPS CLOCKS *	15 MIN	~ 150 ps		
	POLAR MOTION	6 HRS	~ 40 $\mu$ s		
	LENGTH OF DAY	6 HRS	~ 10 $\mu$ s		
RAPID (IGR)	GPS ORBITS	15 MIN	~ 2.5 cm	Daily at 17:00 UTC	17 – 41 Hours
	GPS CLOCKS †	5 MIN	~ 75 ps (RMS)		
	POLAR MOTION	1 DAY	~ 40 $\mu$ s		
	LENGTH OF DAY	1 DAY	~ 10 $\mu$ s		
FINAL (IGS)	GPS ORBITS	15 MIN	~ 2.5 cm	Weekly on Wednesday or Thursday	11 – 17 Days
	GLONASS ORBITS	15 MIN	~ 5.0 cm		
	GPS CLOCKS †	5 MIN	~ 75 ps (RMS)		
	POLAR MOTION	1 DAY	~ 30 $\mu$ s		
	LENGTH OF DAY	1 DAY	~ 10 $\mu$ s		

\* Only satellite clocks are reduced in the Ultra Rapid products.

† Both satellite and station clocks are reduced but **not** all IGS network station clocks.



The current IGS timescale is formed for both the IGS rapid and final products and is derived using a standard Kalman Filter approach.

Kalman Filter was introduced in IGS2.0 version. This second version was implemented in 2011 with reprocessing computed from 2010.

### Specifications for IGST

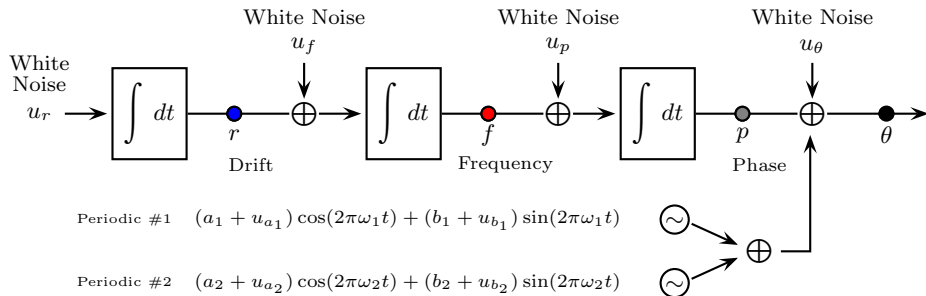
- Consists of an average of 50 – 60 positively weighted member clocks.
- Timescale is generated and exchanged with the IGS data clock reference for the Rapid and Final products.
- Stability performance as low as  $E-16$  for longer averaging intervals.
- Steers to UTC via **AMC2** or **USNO**. Goal is towards **UTC(USNO)**.

### Timescale Features

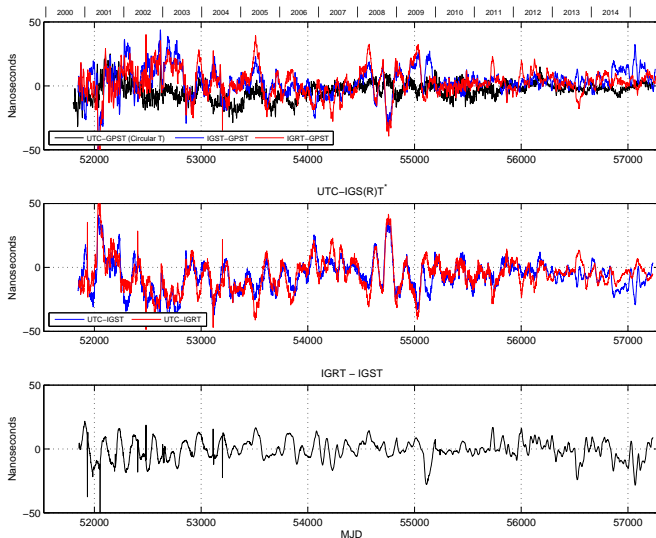
- Institutes a harmonic component into model for all satellite clocks.
- Automated break detection responds to phase and frequency breaks in clock data as well as day-by-day boundaries.
- Steering achieved using Linear Quadratic Gaussian Steering Algorithm.

# General IGS Clock Model

- Filter uses a four state clock model for all station clocks. The total phase state incorporates additional white noise process.
- For satellite clocks, two fixed period harmonics are estimated and added to the total phase state. Hence, some clocks have 8 states.



# IGS(R)T Offset from UTC

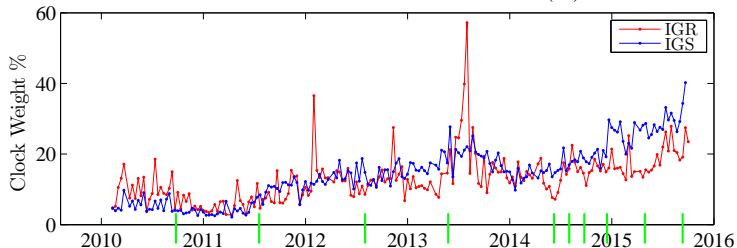


\* Assumes that GPS Time via Circular T is equivalent to GPST

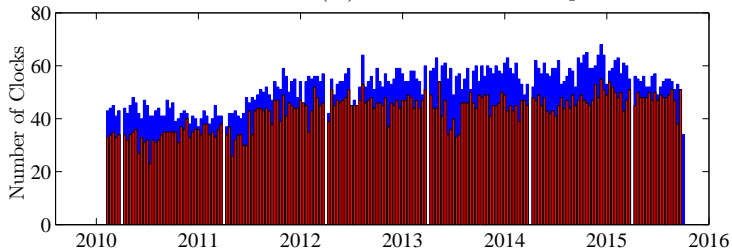
U.S. Naval Research Laboratory 04-Sep-2015, 17:51

# GPS Clock Frequency Weight Contribution

## GPS Clock Contribution to IGS(R)T



## Size of IGS(R)T Clock Membership



## Ground Stations Reduced in Combinations

These tables show some common stations that are weighted in the timescale over the first 257 days of year 2015.

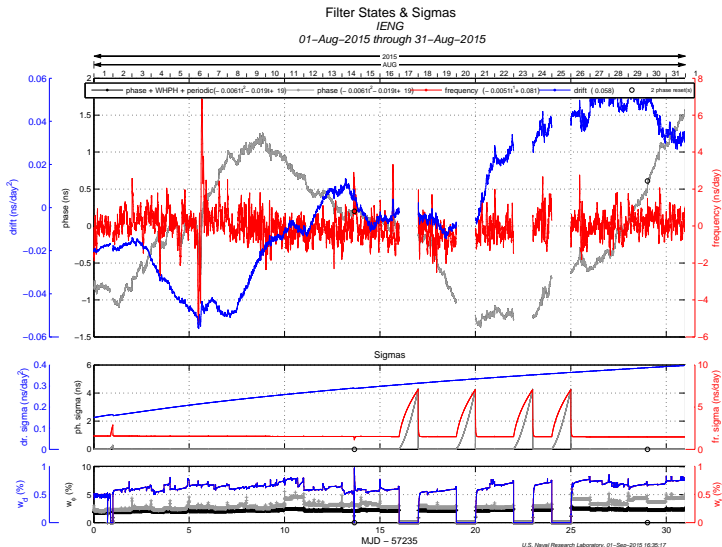
### Stations with IGS & UTC (Partial List)

Station			IGST			IGRT		
IGS	UTC	Location	Days	$w_p$	$w_f$	Days	$w_p$	$w_f$
BJNM	NIM	Beijing CHINA	59	4.31	4.30	0	--	--
IENG	IT	Torino ITALY	38	2.31	0.89	239	3.77	3.85
NIST	NIST	Boulder CO USA	0	--	--	212	4.80	4.80
OPMT	OP	Paris FRANCE	223	4.37	4.38	1	4.86	4.96
PTBB	PTB	Braunschweig GERMANY	233	4.44	4.44	249	4.85	4.84
SFER	ROA	San Fernando SPAIN	225	4.36	2.21	6	5.16	3.53
SPTO	SP	Boras SWEDEN	130	3.69	3.68	194	4.66	4.66
TWTF	TL	Chung-Li TAIWAN	119	4.32	4.31	113	5.07	5.07
USNO	USNO	Washington DC USA	73	3.58	1.09	58	4.37	4.36
WAB2	CH	Bern SWITZERLAND	231	1.64	1.97	238	2.13	0.11



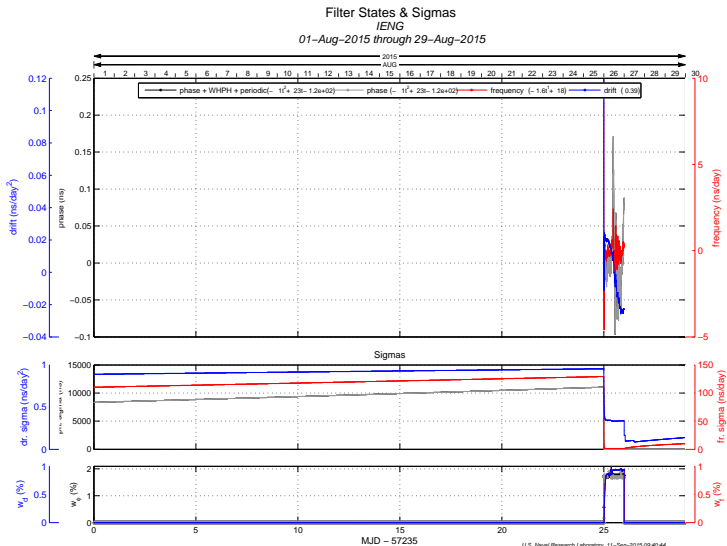
# Case Observation: IENG Rapid Product Estimates

Data is mostly present for the rapid product.



# Case Observation: IENG Final Product Estimates

Data is largely absent for the final product.



### UTC(*k*) Laboratory Inclusion

- UTC labs occasionally fall from IGS(R)T due to Analysis Center computation changes and/or drop outs. This is especially more prominent in IGR.
- Request that Analysis Centers utilize some collection of UTC(*k*) labs to allow improved IGS(R)T stability and UTC steering (as best possible / if possible). Request at next Governing Board Meeting in [December 2015 @ AGU]
- Goal via steering to these references is to maintain

$$|\text{UTC} - \text{IGS(R)T}| < 10 \text{ ns}$$

### Satellite Clock Models

- Improvements to the initialization of clock states and covariances are being timescale filter. This will assist with false starts for GPS clocks and/or resets.
- Increase the contribution of GNSS clocks in IGS(R)T; in particular, include from Galileo, Glonass and Beidou as data becomes available after MGEX project complete. [Longer term timeline]
- GPS (in future, GNSS) clocks are nearly always part of the IGS combinations.



For more information on the IGS core products, experiments and working groups:

[www.igs.org](http://www.igs.org)

For suggestions or requests for the Clock Products:

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