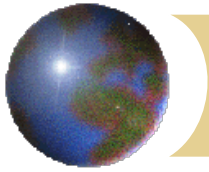


# *Gravity measurements supporting Kibble balances*

*Vojtech Pálinkáš*



Research Institute of Geodesy, Topography and Cartography  
Geodetic Observatory Pecný, Czech Republic



# *Outline*

**1) Definition of „gravity“ and „free-fall“ acceleration**

**2) What is needed for Kibble balance?**

**3 components and methods/technique for determination of:**

- spatial „g“ variations,
- temporal „g“ variations,
- absolute „g“,

**3) Uncertainty of absolute „g“ measurements, key systematic effects**

**4) Conclusion: Uncertainty of different approaches of „g“ determination for Kibble balance**



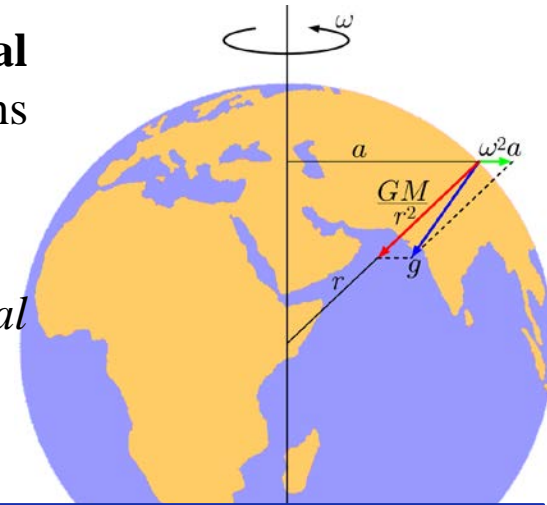
# Definitions

In geodesy, the Earth's Gravity Field is described by **non-inertial system** – geocentric terrestrial reference system (including oceans and atmosphere) :

*gravity potential*  $W = \text{gravitational. } p. U + Q \text{ centrifugal } p.$

*gravity acceleration* **grad W = g = gravitation b + z centrifugal acceleration**

$g = |\mathbf{g}|$  (magnitude of gravity acceleration)



*Not only gravitational force is relevant  $\Rightarrow$  the usual term of „gravitational“ acceleration is incorrect in this case*

International Earth Rotation and Reference Systems Service (IERS)  
Service International de la Rotation Terrestre et des Systèmes de Référence

IERS Technical Note No. 36

*consensus quantity*

IERS Conventions (2010)

Gérard Petit<sup>1</sup> and Brian Luzum<sup>2</sup> (eds.)

IERS Conventions Centre

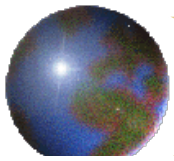
$$g = g_F + \Delta g_T + \Delta g_{Atm} + \Delta g_{Pol}$$

**gravity acceleration** = free-fall acceleration measured by absolute gravimeters corrected by set of conventional corrections for tides, polar motion and atmosphere variation

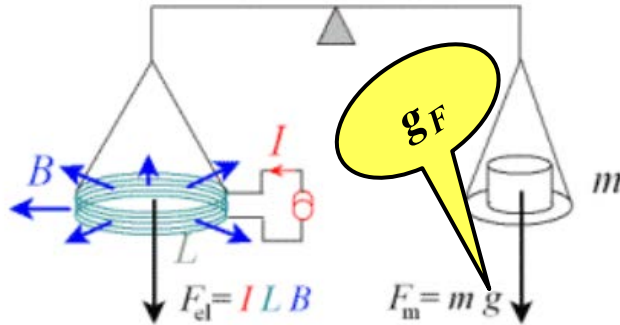
*needed for Kibble balance*

<sup>1</sup> Bureau International des Poids et Mesures (BIPM)

<sup>2</sup> US Naval Observatory (USNO)



# Required uncertainty

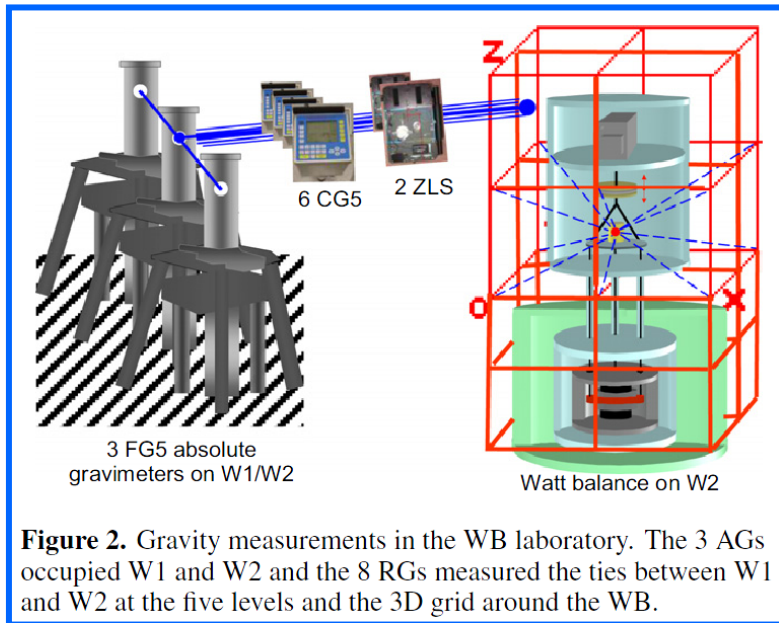


Target  $u = 10 \mu\text{g} \Rightarrow$  relative standard uncertainty of  $1\text{E-}8$   
 $g_F$  contribution should be  $<5\text{E-}9 \Rightarrow 5\text{E-}8 \text{ m}\cdot\text{s}^{-2}$  (50 nm·s<sup>-2</sup>)

**at the centre of mass and time of the KB experiment**

**5  $\mu\text{Gal}$**

## BASIC CONCEPT

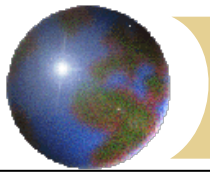


**Figure 2.** Gravity measurements in the WB laboratory. The 3 AGs occupied W1 and W2 and the 8 RGs measured the ties between W1 and W2 at the five levels and the 3D grid around the WB.

- 1) Measure **absolute g**
- 2) Measure/model temporal **gravity variations** (tides, polar motion, atmosphere, hydrosphere, geodynamics)

*obtain  $g_F(t)$*

- 3) Transfer  $g_F(t)$  to the centre of mass



# Transfering „g“ to the centre of mass

IOP PUBLISHING  
Metrologia 45 (2008) 265–274

## Micro-gravity investigation of the LNE watt balance

Sébastien Merlet<sup>1</sup>, Alexander Kopaev<sup>2</sup>, Michel Gérard Geneves<sup>4</sup>, Arnaud Landragin<sup>1</sup> and

IOP Publishing | Bureau International des Poids et Mesures

Metrologia 51 (2014) S32–S41

## Gravimetry for water

J O Liard<sup>1</sup>, C A Sanchez<sup>1</sup>, B M Wood<sup>1</sup>, A

<sup>1</sup> National Research Council Canada, 1200 Montreal Road  
<sup>2</sup> Natural Resources Canada, 615 Booth St, Ottawa, ON, K

IOP Publishing | Bureau International des Poids et Mesures

Metrologia 54 (2017) 445–453

## Self-attraction mapping and an update on local gravitational acceleration measurement in BIPM Kibble balance

Shisong Li, Franck Bielsa, Adrien Kiss and Hao Fang

Metrologia

<https://doi.org/10.1088/1681-7575/aa71e1>

Carefull **3D gravity mapping** is needed ( $\uparrow 3 \text{ mm} \approx -1 \mu\text{Gal}$ ) including determination of the **self-attraction** effect  $\Rightarrow$  standard uncertainty of **2.0  $\mu\text{Gal}$**

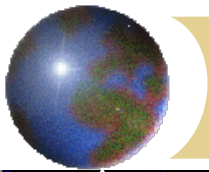
**Well calibrated** relative gravimeters are needed avoiding those having significant **magnetic sensitivity**.

The gravity difference should be computed from the position of **AG** where  $g$  is invariant of the gradient - **effective position of the free-fall** (1.22 m / 1.27 m for FG5/FG5X)

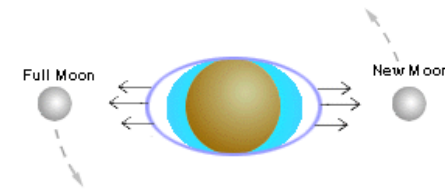
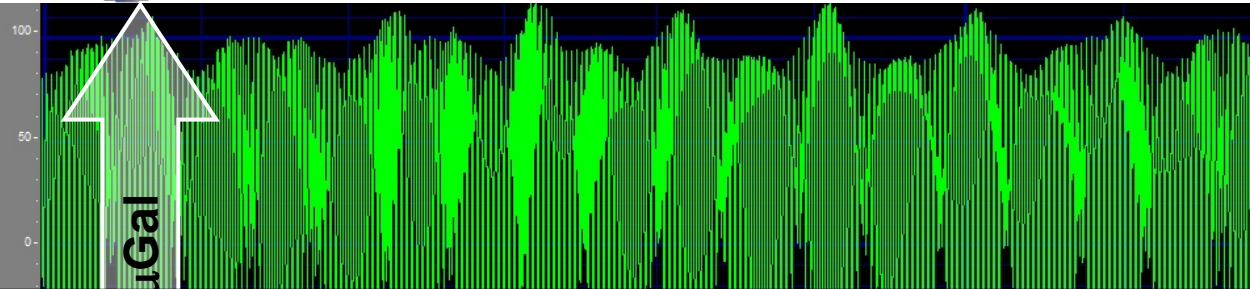
$$(5^2 - 2^2)^{0.5} = 4.6 \mu\text{Gal}$$

**contribution from determination of absolute  $g_F$  (including temporal variations)**

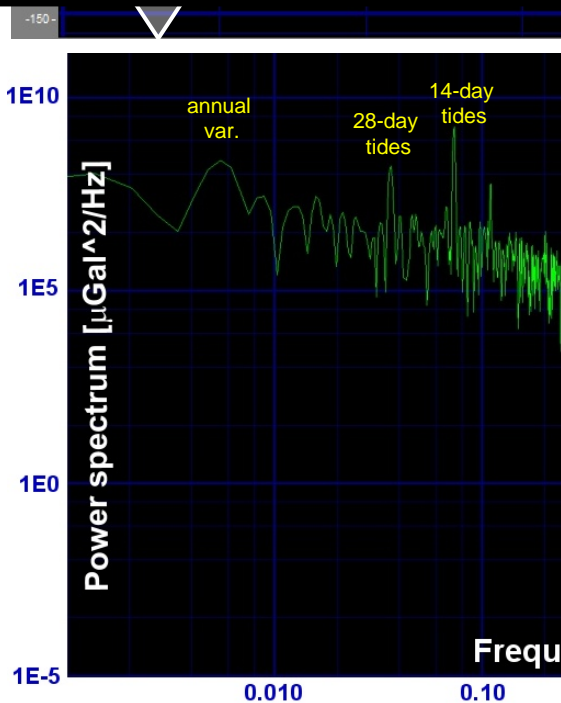




# Temporal variations - Tides



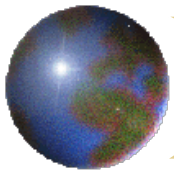
Always check if the **permanent tide (M0+S0, frequency = 0.000)** are treated by the same way for tidal variations and for absolute  $g$



## Easily predictable effect

Possibility to determine:

- 1) **modelling** only (solid tides + ocean loading)  $\pm 1 \mu\text{Gal}$
- 2) **6-months observations** with well calibrated relative gravimeter  $\pm 0.2 \mu\text{Gal}$ . Tidal parameters for main tidal waves are determined (**ocean tides** are included).  
No need to measure exactly on the site of Kibble balance experiment. Tidal parameters have **large spacial validity** if the ocean tides are small – e.g. differences between using parameters from Prague or Vienna reach below  $0.1 \mu\text{Gal}$



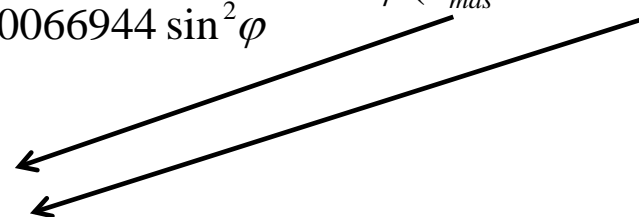
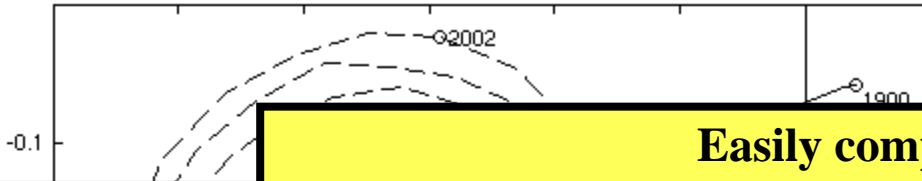
# Temporal variations - polar motion

The motion of the rotation axis of the earth **relative to the crust**. Main components: a free oscillation with period about **435 days** (Chandler wobble) and an **annual oscillation**.

The momentary latitude is changing  $\Rightarrow$  **change of the centrifugal acceleration**

$$\Delta g_{Pol} = \frac{19.074}{\sqrt{1 - 0.0066944 \sin^2 \varphi}} \sin 2\varphi (x_{mas} \cos \lambda - y_{mas} \sin \lambda) / \mu\text{Gal}$$

Polhody over 2001-2006 and mean pole since 1900

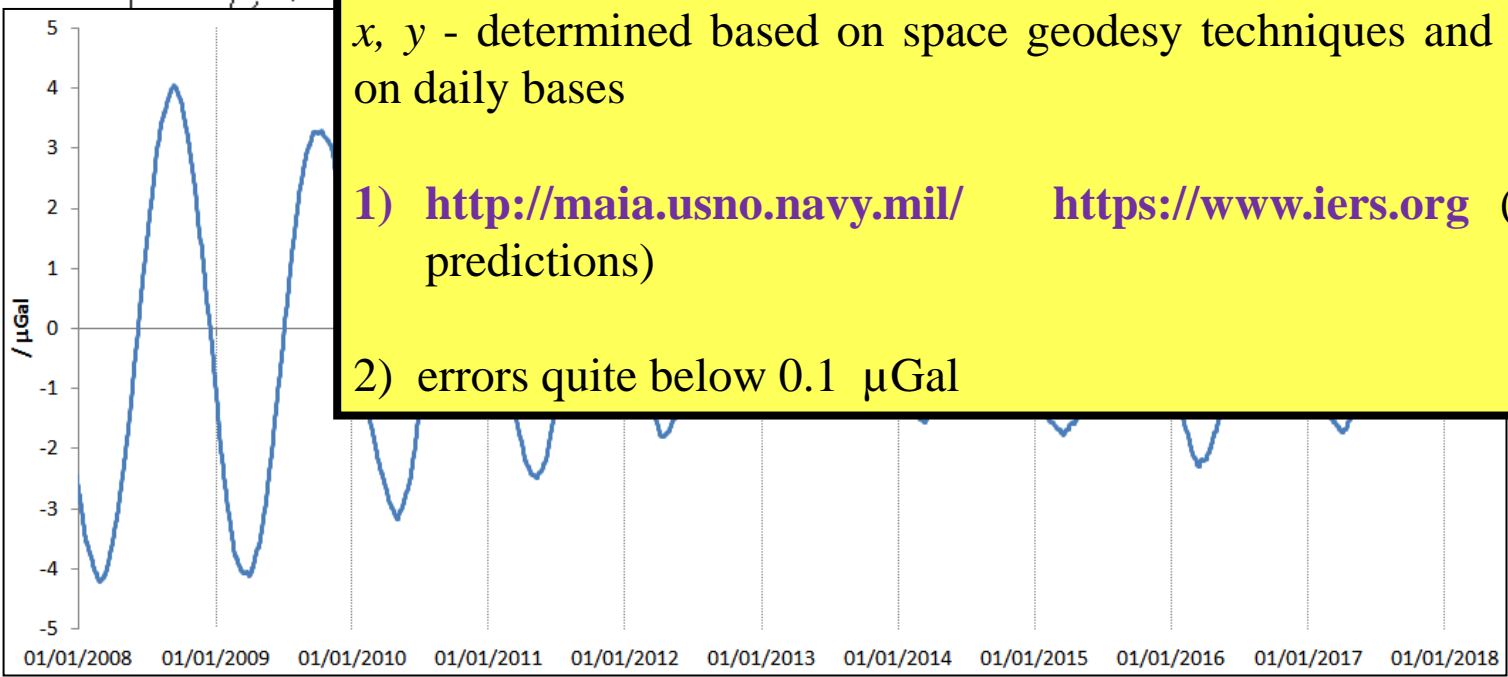


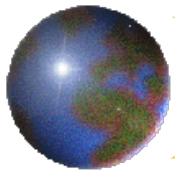
**Easily computable effect**

$x, y$  - determined based on space geodesy techniques and published on daily bases

1) <http://maia.usno.navy.mil/>      <https://www.iers.org> (including predictions)

2) errors quite below 0.1  $\mu\text{Gal}$





# *Temporal variations – Atmosphere*

DIN 5450 (ISO 2533:1975) Standard Atmosphere  $\Rightarrow$  Normal pressure (depends on elevation  $H$ ):

$$p_n = 1013,25 (1 - 0,0065 H / 288,15)^{5,2559} \quad \text{hPa}$$

Simply model/correction using single admittance:  $\Delta g_p = 0,3 (p - p_n) \quad \mu\text{Gal}$

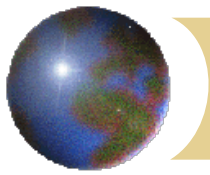
Pressure variations up to 60 hPa at given site  $\Rightarrow$  variations of about **18  $\mu\text{Gal}$**

- the simple model works well in most of cases (errors up to 2  $\mu\text{Gal}$  with respect to 3D model)  **$u = \pm 1.0 \mu\text{Gal}$**

- especially at high elevations, the single admittance should be verified

- atmospheric pressure has to be measured simultaneously with KB experiment (daily variations up to 20 hPa)

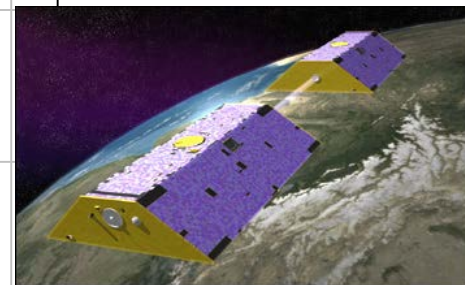
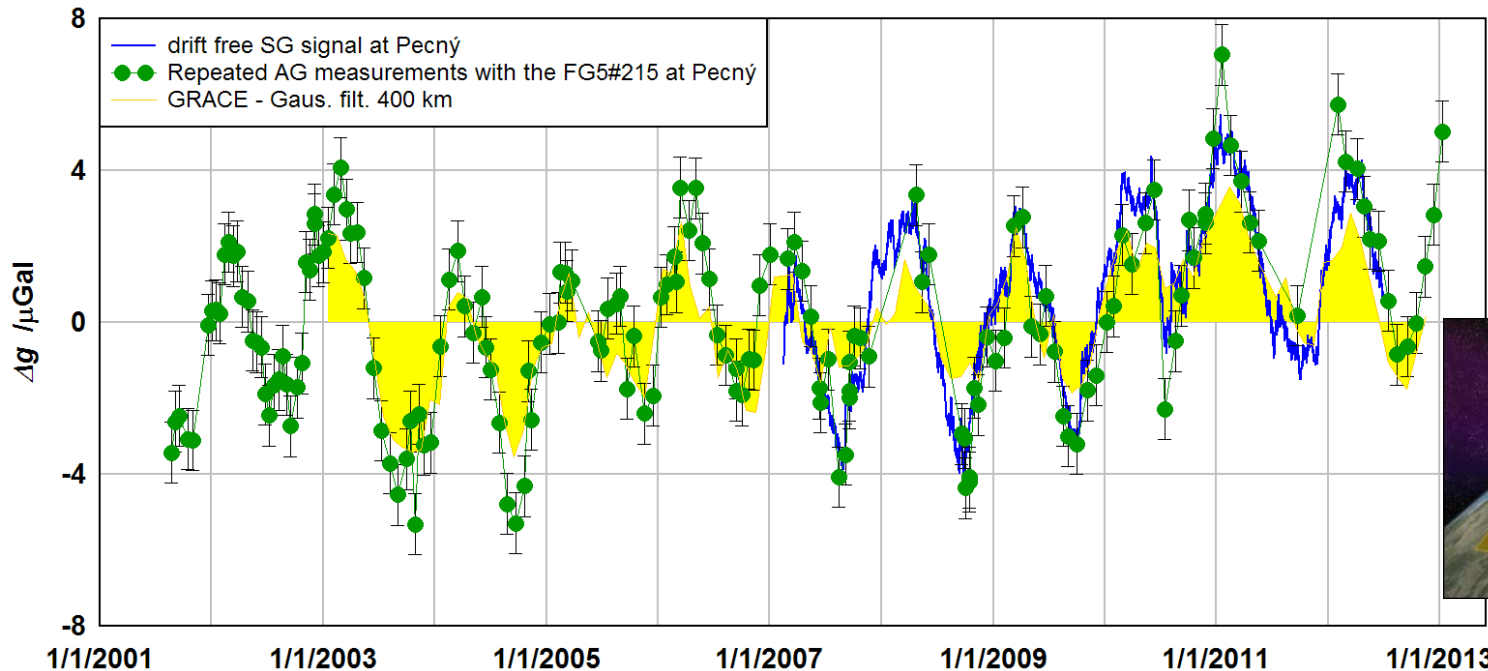
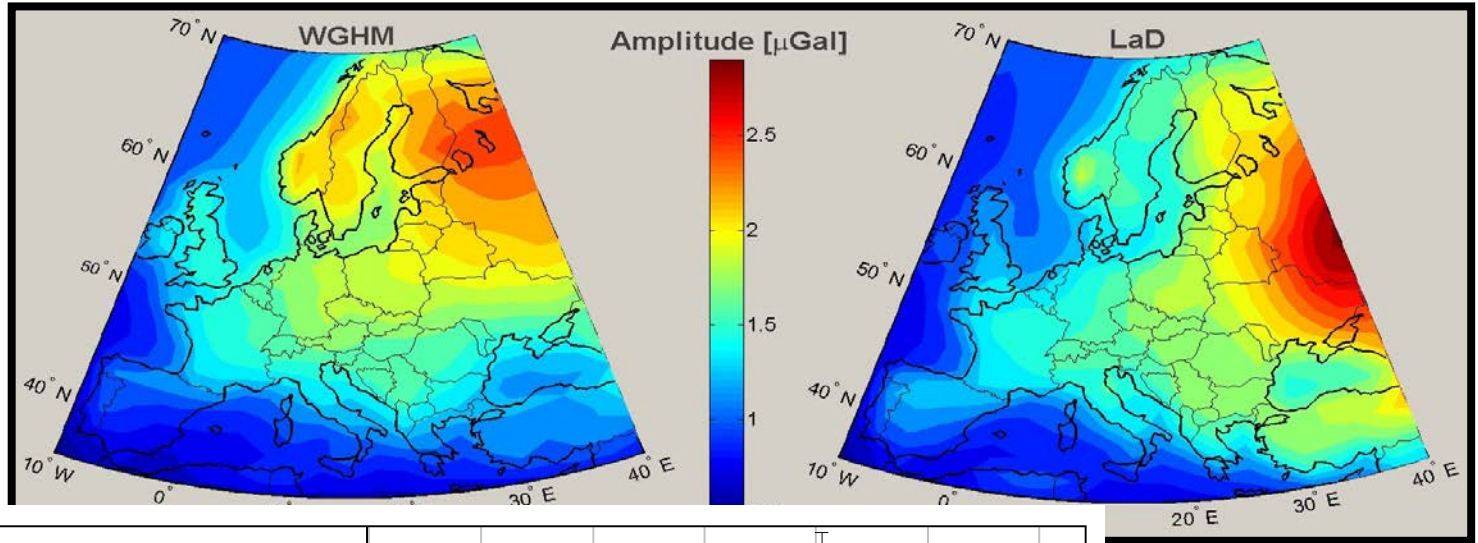


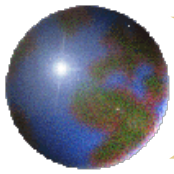


# Temporal variations – Global hydrology

Continental water storage variations (hydrological models WGHM, LaD, etc. ) – validated by GRACE

**“g” variations up to 6  $\mu\text{Gal}$  in Europe  
Maximum g in autumn**





# Temporal variations – Local hydrology

Geophysical Journal International

Geophys. J. Int. (2014)

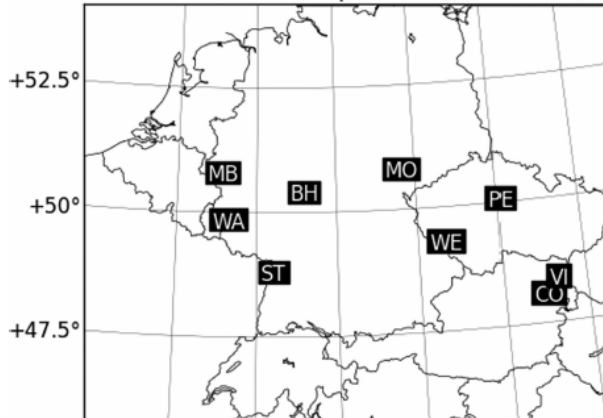
doi: 10.1093/gji/ggt524

Geophysical Journal International Advance Access published January 29, 2014

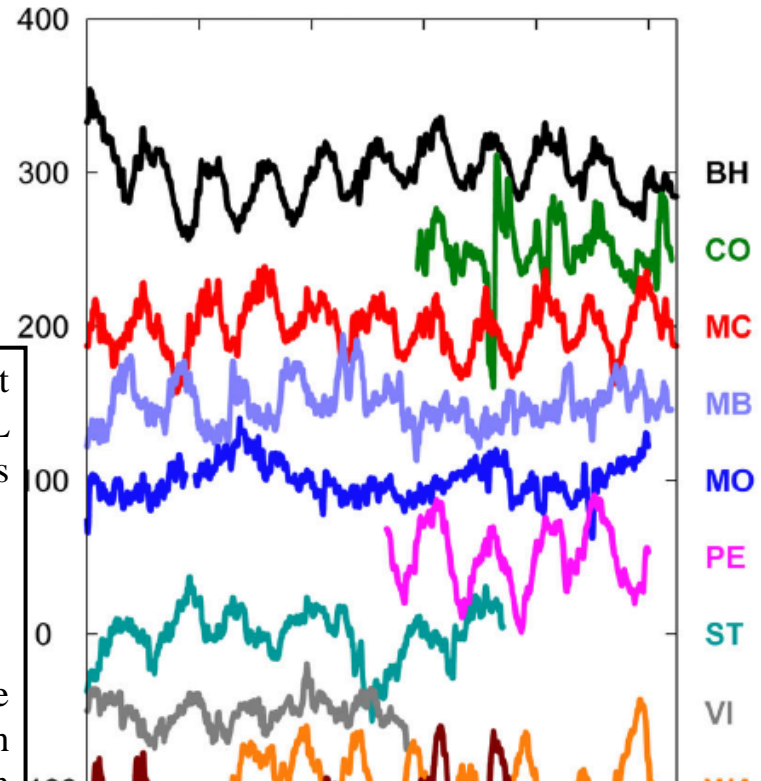
### The quest for a consistent signal in ground and GRACE gravity time-series

Michel Van Camp,<sup>1</sup> Olivier de Viron,<sup>2</sup> Laurent Métivier,<sup>3</sup> Bruno Meurers<sup>4</sup> and Olivier Francis<sup>5</sup>

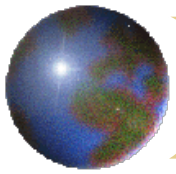
Station positions



The signal is variable at stations due to LOCAL hydrology (100 m radius is critical)  
Seasonal effect is dominant.  
Amplitudes depends on the hydrology and localization of the station



**Hardly modeled effects**  
Seasonal variations approaching 10  $\mu$ Gal are quite usual  
The effect should be **verified by measurements** (carried out for different periods of the year) – at least to determine the “hydrological sensitivity” of the station  
Localization of the **Kibble balance** and “g” measurements should be **close to each other**

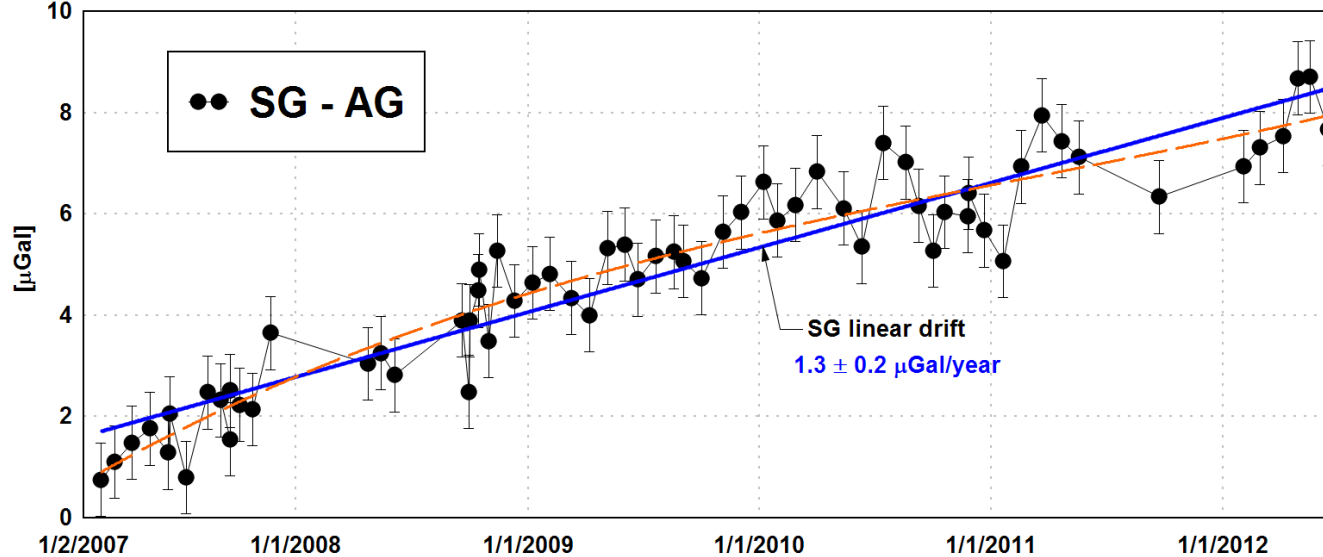
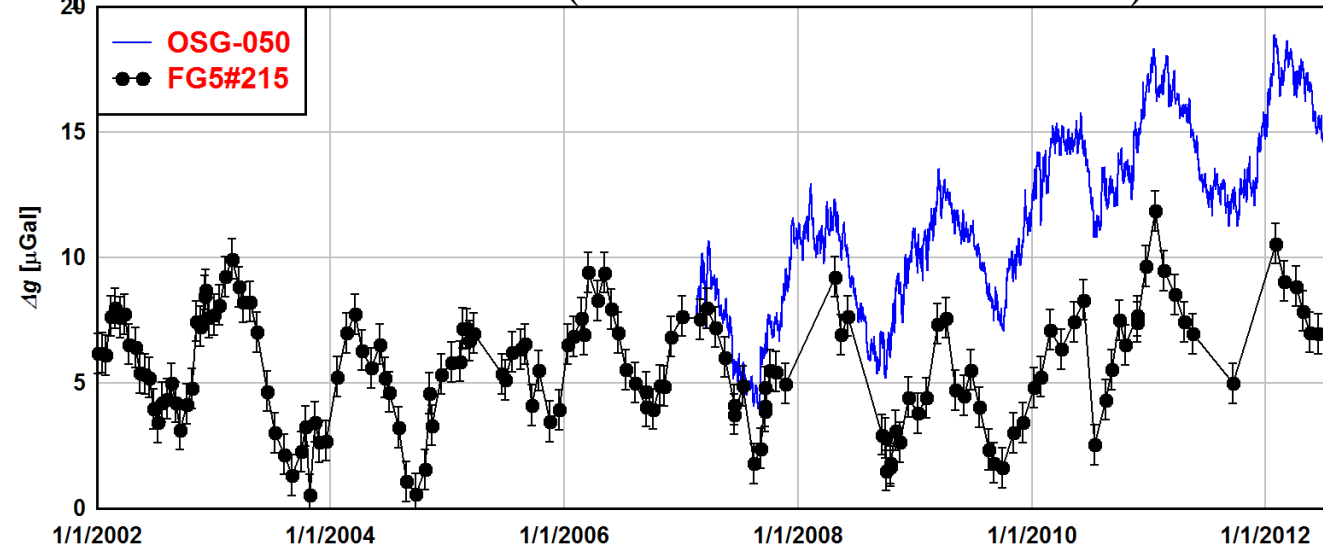


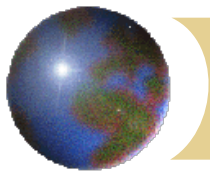
# Combination of AG and SG

In situ geodynamic stations: used for the gravity variations in periods from few minutes (free-oscillations of the Earth) to decades



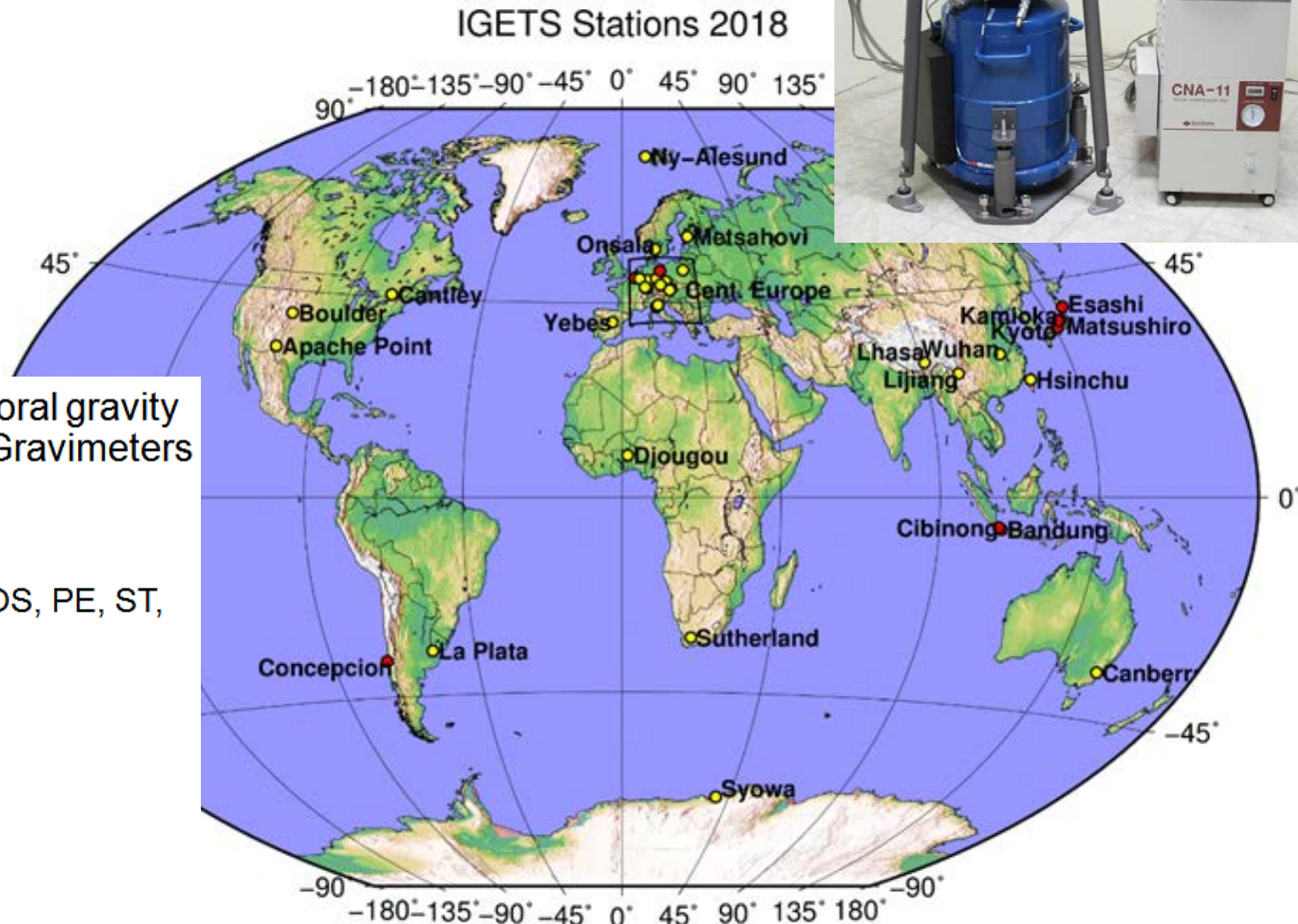
- relative values
- precision  $< 0.1 \mu\text{Gal}$
- continuous registration
- high temporal resolution





# Worldwide SG stations

International Geodynamics and Earth Tides Service (IGETS)



**Continuous monitoring** of temporal gravity variations with Superconducting Gravimeters

Selection from active 21 (+2) stations:

Europe (13+1):

BG, BH, CO, MC, MB, ME, MO, NY, OS, PE, ST, WE, YS, [BF]

North America (3): AP, BO, CA

South America (1): LP

Asia:

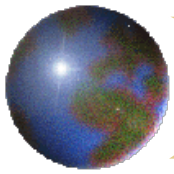
China (3): LH, LI, WU

Japan (1+2): MA, [MI, IS]

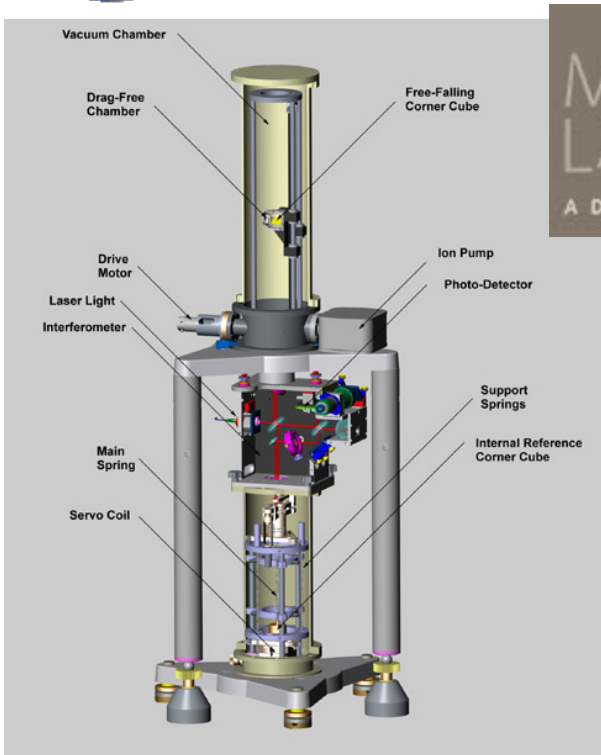
Africa (1+1): SU, [DJ]

Antarctica (1): SY

<http://isdg.gfz-potsdam.de/igets-data-base>



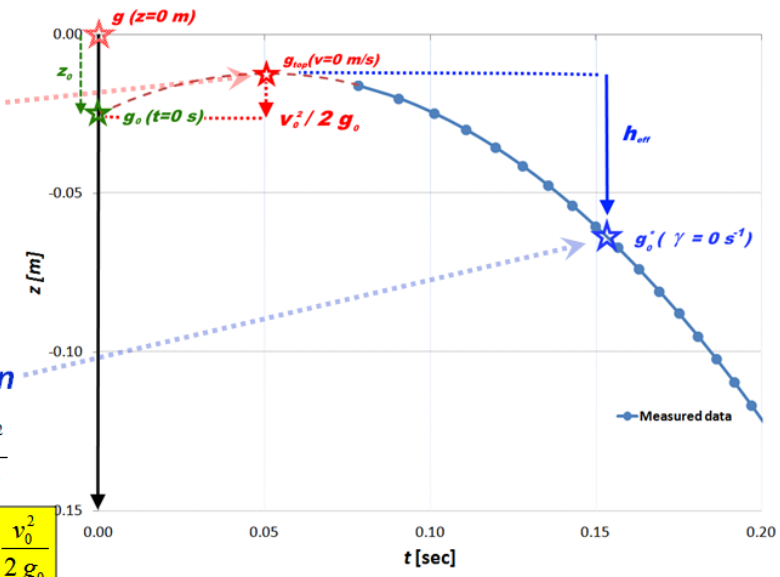
# FG5/X absolute gravimeters



Most accurate and commercial available absolute gravimeters

Corner-cube absolute gravimeter  
The freely falling test mass is tracked by laser interferometer

$$z_i = z_0 + v_0 (t_i + \frac{W_{zz}}{6} t_i^3) + \frac{1}{2} g_0 (t_i^2 + \frac{W_{zz}}{12} t_i^4),$$



Top of the drop

$$v = \frac{dz}{dt} = 0 \quad z = z_0 - \frac{v_0^2}{2g_0}$$

$$g_{top} = g_0 - \gamma \frac{v_0^2}{2g_0}$$

Effective position

$$z_i = z_0^* + v_0^* t_i + g_0^* \frac{t_i^2}{2}$$

$$h_{eff} = \frac{g_0(\gamma_A) - g_0^*(\gamma = 0)}{\gamma_A} + \frac{v_0^2}{2g_0}$$

Absolute gravimeter:

- based upon physical standards
- no drift
- uncertainty:  $\pm 2.5 \mu\text{Gal}$
- Long-term reproducibility :  $\pm 1.5 \mu\text{Gal}$
- observation epochs



# CMCs

## **Austria, BEV (Bundesamt für Eich- und Vermessungswesen)**

[Complete CMCs in Mass and related quantities for Austria](#) (.PDF file)

Gravitational acceleration. On (stable) site, **9.75 m/s<sup>2</sup> to 9.85 m/s<sup>2</sup>**  
Absolute expanded uncertainty ( $k = 2$ , level of confidence 95 %) in m/s<sup>2</sup>: **1.0E-07**  
Absolute measurement  
Ambient temperature: (21 ± 5) °C

## **Finland, FGI (Finnish Geospatial Research Institute)**

[Complete CMCs in Mass and related quantities for Finland](#) (.PDF file)

Gravitational acceleration. On (stable) site, **9.75 m/s<sup>2</sup> to 9.85 m/s<sup>2</sup>**  
Absolute expanded uncertainty ( $k = 2$ , level of confidence 95 %) in m/s<sup>2</sup>: **8.0E-08**  
Free fall experiment  
Ambient temperature: 21 °C ± 8 °C  
Approved on 03 January 2007

## **Italy, INRIM (Istituto Nazionale di Ricerca Metrologica)**

[Complete CMCs in Mass and related quantities for Italy](#) (.PDF file)

Gravitational acceleration. On (stable) site, **9.75 m/s<sup>2</sup> to 9.85 m/s<sup>2</sup>**  
Absolute expanded uncertainty ( $k = 2$ , level of confidence 95 %) in m/s<sup>2</sup>: **1.5E-07**  
Absolute measurement  
Ambient temperature: 23 °C ± 10 °C  
Approved on 03 January 2007

## **Switzerland, METAS (Federal Institute of Metrology)**

[Complete CMCs in Mass and related quantities for Switzerland](#) (.PDF file)

Gravitational acceleration. On (stable) site, **9.75 m/s<sup>2</sup> to 9.85 m/s<sup>2</sup>**  
Absolute expanded uncertainty ( $k = 2$ , level of confidence 95 %) in m/s<sup>2</sup>: **8.0E-08**  
Absolute measurement  
Ambient temperature: (20 ± 5) °C  
Approved on 02 July 2008

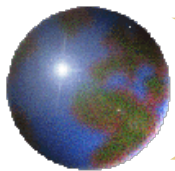
## **Ukraine, NSC "Institute of Metrology" (National Scientific Centre "Institute of Metrology")**

[Complete CMCs in Mass and related quantities for Ukraine](#) (.PDF file)

Gravitational acceleration. On (stable) site, **9.77 m/s<sup>2</sup> to 9.85 m/s<sup>2</sup>**  
Absolute expanded uncertainty ( $k = 2$ , level of confidence 95 %) in m/s<sup>2</sup>: **2.08E-07**  
Absolute measurement  
Ambient temperature: 14 °C to 34 °C  
Approved on 21 June 2017  
Internal NMI service identifier: NSCIM-M-8.1.1/7

$$u = 4.0 \mu\text{Gal}$$

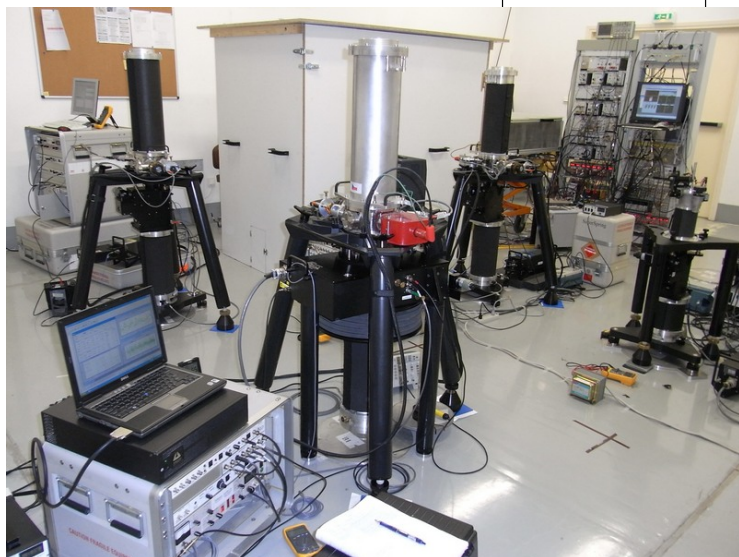
**How accurate are the absolute measurements?**



# Comparisons of absolute gravimeters

## ICAGs – at BIPM from 1981 to 2009

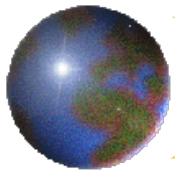
1981-82 7 AG	1985 6 AG	1989 10 AG	1994 11 AG	1997 17 AG	2001 15 AG	2005 19 AG	2009 22 AG
IMGC, Italy GABL, USSR JAEGER, BIPM NIM, China Hammond, USA Sakuma, static array Faller, USA	IMGC GABL JAEGER, BIPM NIM-1 Zumberge, USA  JILAg-1	IMGC GABL  NIM-1 NAO, Japan  Sakuma, static array*  JILAg-4 JILAg-2 JILAg-3 JILAg-5 JILAg-6	IMGC  JAEGER, Japan    JILAg-2 JILAg-3 JILAg-5 JILAg-6  FG5-101 FG5-102 FG5-104 FG5-107 FG5-108	IMGC GABL NIM-2A NIM-2B* ZZB  JILAg-2 JILAg-3 JILAg-5 JILAg-6  FG5-101 FG5-103 FG5-105 FG5-107 FG5-108 FG5-202 FG5-206	IMGC A10-b02* A10-03  JILAg-2 JILAg-5 JILAg-6  FG5-101 FG5-103 FG5-105 FG5-108 FG5-202 FG5-204 FG5-206 FG5-209 FG5-211 FG5-213 FG5-216 FG5-221 FG5-224 FG5-301*	IMGC-2 GABL A10-8 FGC-01 GABL-01 TBG-01 JILAg-2 JILAg-6 FG5-101 FG5-108 FG5-202 FG5-206 FG5-209 FG5-211 FG5-213 FG5-215 FG5-216 FG5-221 FG5-224 FG5-228	IMGC-2* CAG-01 NIM-02 MPG-2 A10-05 A10-14 A10-20 JILAg-6 FGL-103 FG5-101 FG5-102 FG5-105 FG5-209 FG5-213 FG5-215 FG5-220 FG5-221 FG5-224 FG5-228 FG5-230 FG5-233 FG5-238 13 FG5
	1 <sup>st</sup> JILAg	5 JILAg	5 FG5	7 FG5	11 FG5	12 FG5	13 FG5



2003, 2007 – Walferdange in Luxembourg

3 CIPM\_KC: 2009 (11 KC + 10 PS), 2013 Walferdange (10 KC + 15 PS), 2017 Beijing (13 KC + 17 PS);

3 EURAMET\_KC + PS: 2011, 2015, 2018



# *Comparisons of absolute gravimeters*

The KCRV is defined by KC gravimeters only using the weighted constraint

$$\sum w_k \delta_k = 0$$

CCM-KC 2009: 7 from 11 AGs FG5/X

CCM-KC 2013: 8 from 10 AGs FG5/X

CCM-KC 2017: 12 from 13 AGs FG5/X

**COMPARISONS – more than 90% of weights are given by FG5/X gravimeters declaring standard uncertainties of 2-3  $\mu$ Gal (confirmed at comparisons)**

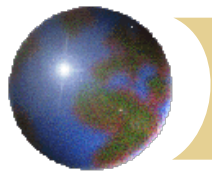
**However, KCRVs are strongly “FG5/X dependent” !!!**

**Possible Systematic effects have to be captured!!!**

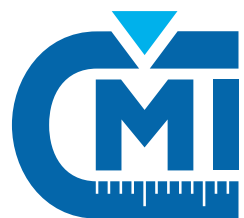
**Another technique have to be used for verification !!!**







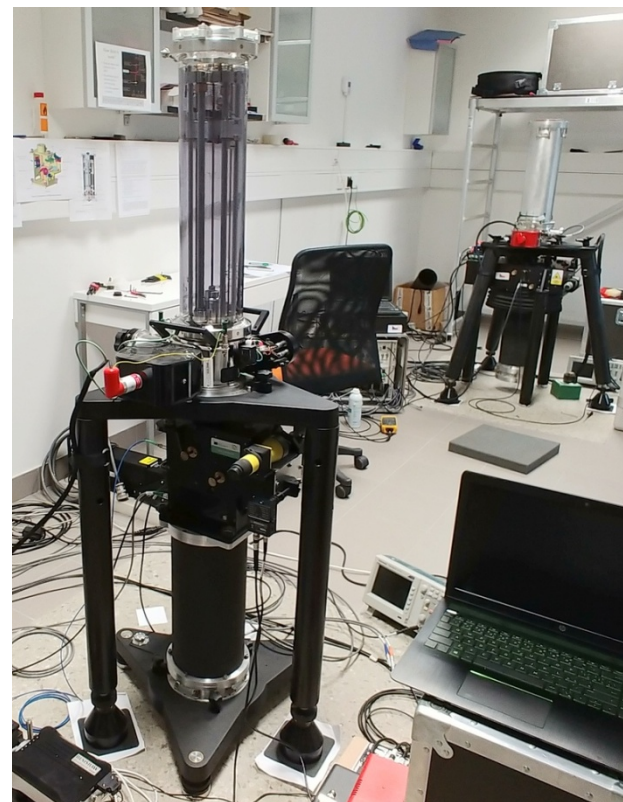
# *Systematic errors of FG5/X*



CZECH  
METROLOGY  
INSTITUTE



Research Institute of  
Geodesy, Topography and  
Cartography



## **Experiments on FG5-215 and FG5X-251:**

- validation of measurement results
- determination of particular systematic errors
- improvement of the original measurement technology
- developing new measurement systems, methods, software, analysis

*Petr Křen et al.*

*Metrologia 53 (2016) 27-40*

*Journal of Geodesy 93 (2019) 27-40*

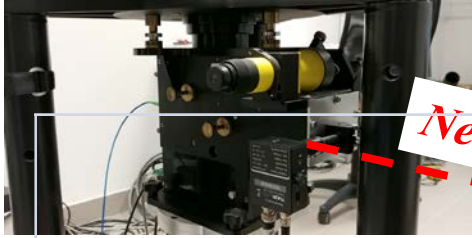
*Metrologia 55 (2018) 451-459*

*Metrologia 54 (2017) 161-170*

*Metrology and Measurement Systems 25 (2018) 701-713*

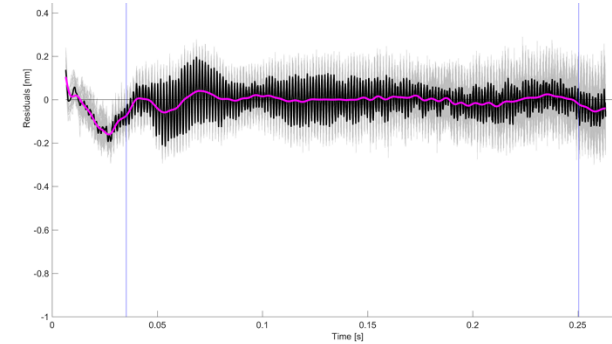


# FG5(X) uncertainty

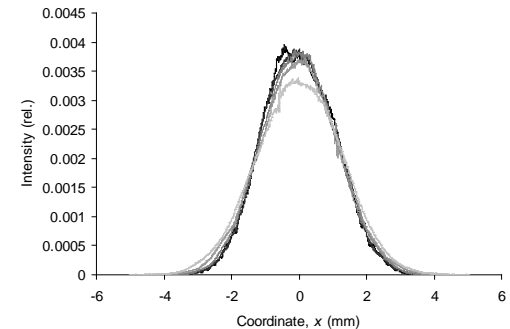


*New system*

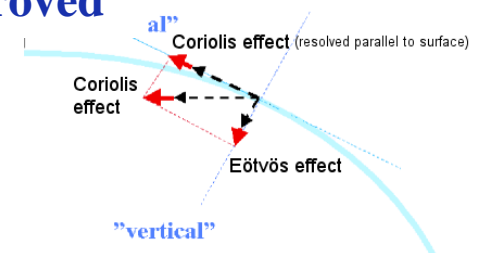
Influence parameters $x_i$	FG5(X) with HS5 system + additional corrections Contribution to the uncert. <i>/ <math>\mu Gal</math></i>	FG5(X) - original system + standard corrections Contribution to the uncert. <i>/ <math>\mu Gal</math></i>
Laser frequency	0.02	0.02
Rb-oscillator frequency	0.02	0.02
<b>Test mass rotation, mechanical effects</b>	<b>0.70</b>	<b>0.70</b>
<b>Air gap modulation, floor recoil, fringe interval</b>	<b>1.15</b>	<b>1.15</b>
Vacuum pressure	0.15	0.15
Self attraction correction	0.20	0.20
Electrostatic effect	0.12	0.12
Magnetic gradient field	0.23	0.23
Temperature sensitivity	0.50	0.50
Determination of the reference instr. height	0.35	0.35
Perturbation due to non-constant gravity gradient	0.20	0.20
<b>Electronic phase shift and timing electronics</b>	<b>0.40</b>	<b>2.00</b>
<b>Impedance mismatch</b>	<b>0.05</b>	<b>0.70</b>
<b>Coriolis effect</b>	<b>0.10</b>	<b>0.60</b>
<b>Verticality of the test beam</b>	<b>0.05</b>	<b>0.60</b>
<b>Diffraction correction</b>	<b>0.45</b>	<b>1.00</b>
<b>Dispersion in cable</b>	<b>0.02</b>	<b>0.50</b>
Setup-error, interferometer alignment	0.90	0.90
	<b>1.88</b>	<b>3.10</b>

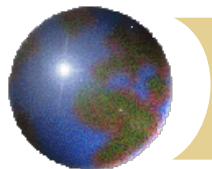


**Investigated**



**Improved**



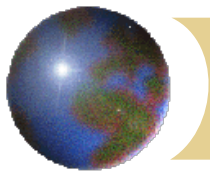


# *FG5(X) Original system bias*

<b>Corrections / <math>\mu\text{Gal}</math></b>	<b>Standardly applied</b>	<b>New corrections</b>	<b>Difference</b>
Speed-of-light	$\bar{t}_i = t_i + \frac{(z_i - z_0)}{c}$	$\bar{t}_i = t_i + \frac{(z_i - z_0)}{c}$	0.0
Self-attraction	-1.2	-1.2	0.0
Diffraction	+1.2	+2.4	+1.2
Distortion (350 mV fringes)	N/A	-2.2	-2.2
Cable length (5 m)	N/A	-1.0	-1.0
Impedance mismatch	N/A	-1.4 / +1.4	?
Verticality	N/A	+0.2 / +1.0	+0.6
Eötvös/Coriolis	N/A	-1.0 / +1.0	?
Air-gap modulation etc.	?	?	?
<b>Sum</b>			<b>-1.4</b>

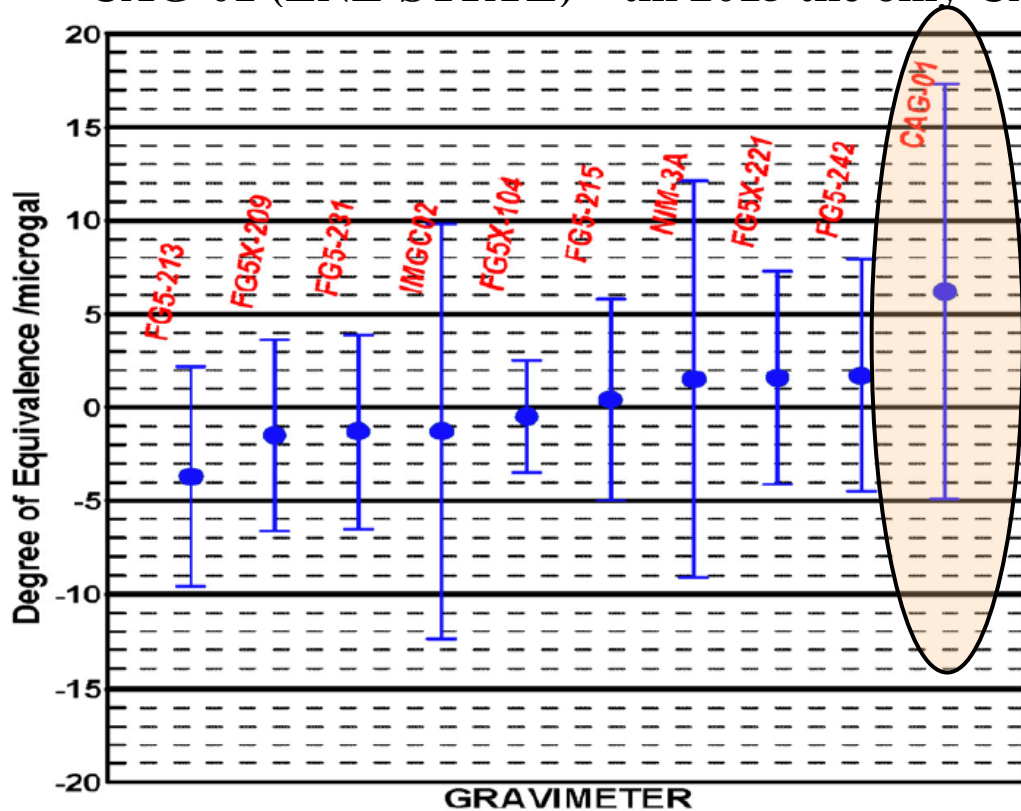
**According to present estimates, the g-values of FG5/X should be too high at present and decreased by -1.4  $\mu\text{Gal}$  in average. However few next effects have to be estimated.**

**Generally, the present bias of KCRV is expected to be up to 2  $\mu\text{Gal}$ .**

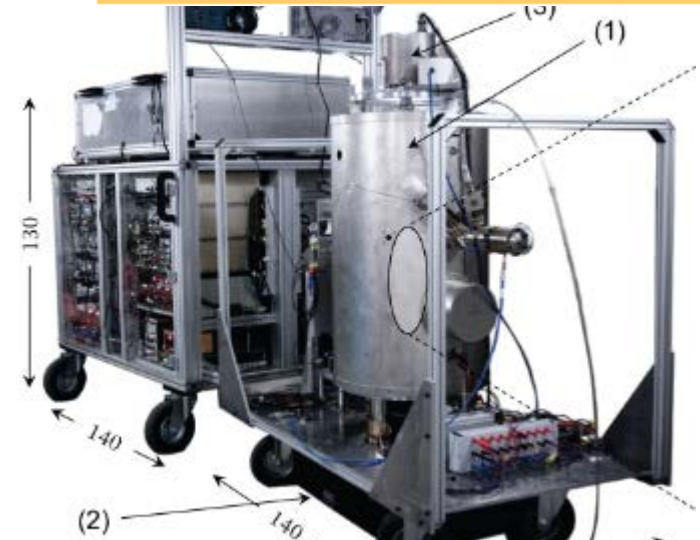


# Comparison with cold atom gravimeters

CAG-01 (LNE-SYRTE) – till 2015 the only CAG at International Comparisons



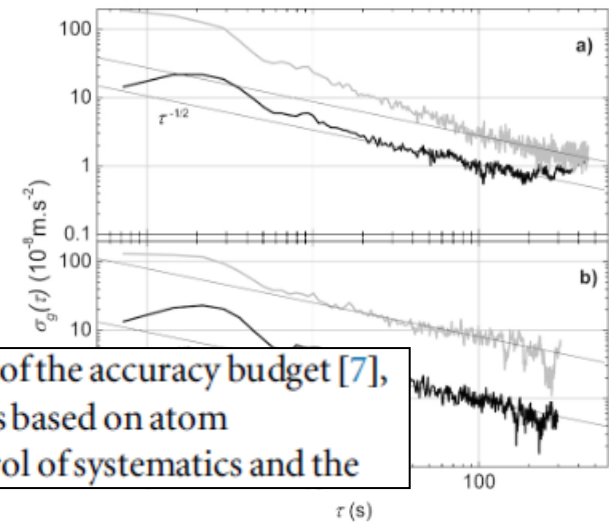
$$\Delta\Phi_{\text{int}} = -\bar{k}_{\text{eff}} \bar{g} T^2 + \delta\Phi_{\text{noise}} + \delta\Phi_{\text{sys}}$$

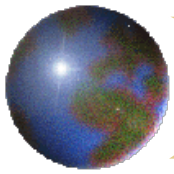


Karcher et al. (2018) *New Journal of Physics* 20

**+5.6 ± 1.3 μGal bias explained by wavefront aberration**

With the above-mentioned improvements, and after a careful re-examination of the accuracy budget [7], accuracies better than 10 nm s<sup>-2</sup> are within reach. This will make quantum sensors based on atom interferometry the best standards in gravimetry. Furthermore, the improved control of systematics and the

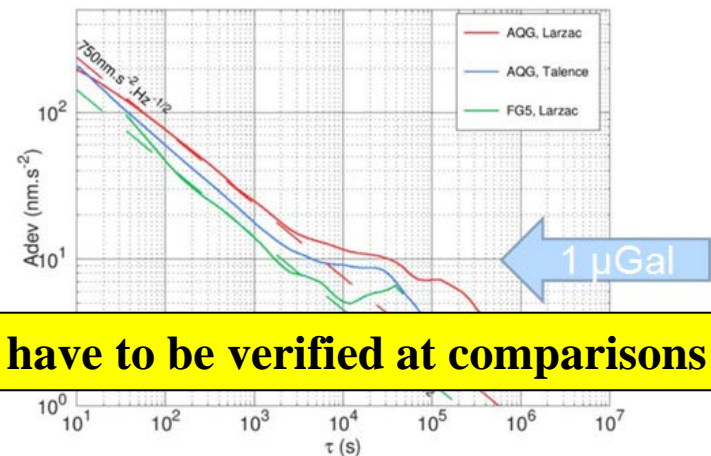
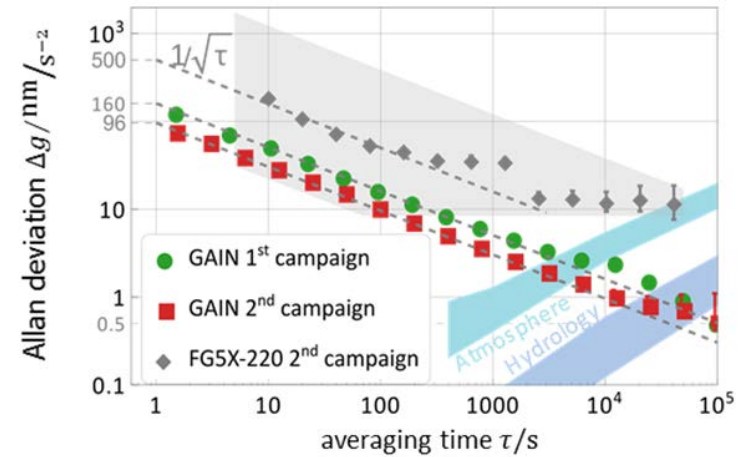
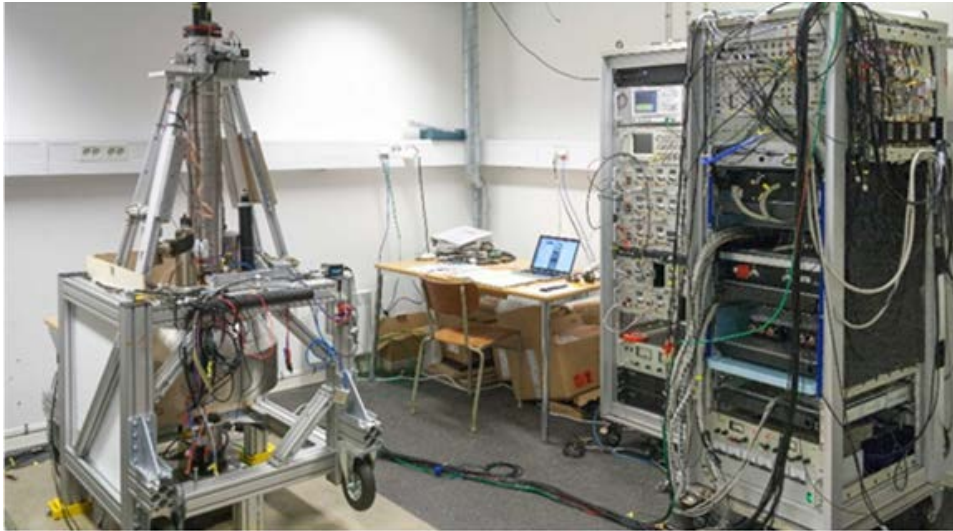




# Comparison with cold atom gravimeters

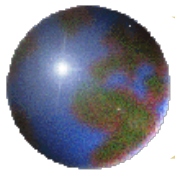
GAIN

Freier et al. 2016, Journal of Physics: Conference Series 723 012050



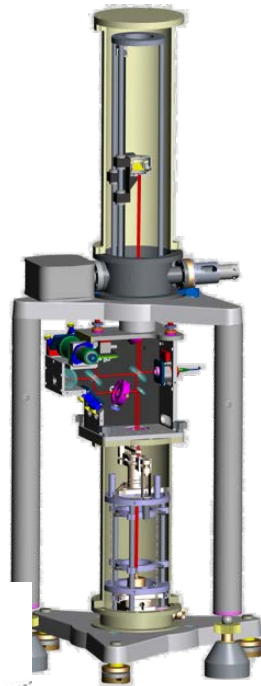
**Nice stabilities are showed but uncertainties have to be verified at comparisons**

Figure 5. Allan deviation (left) and power spectral density (right) of the gravity measurements with AQG-A01 in Larzac (solid red) and Talence (blue), and with FG5#228 in Larzac (solid green). The effective sampling interval of the FG5 was taken as 36 s. The red (resp. green) dashed line in the Allan plot indicates a sensitivity of 750 (resp. 450)  $\text{nm} \cdot \text{s}^{-2} \cdot \text{Hz}^{-1/2}$ .



# Conclusion: Accuracy of $g_F$ 1/3

The most accurate method: Combination of a continuous Superconducting Gravimeter (SG) and Absolute measurements (e.g. once per year)



**Parameter**

**Standard uncertainty /  $\mu\text{Gal}$**

Absolute  $g$ : *FG5X-HS5 (CAG-01) / FG5X*

1.9 / 3.1

Time variability

0.1

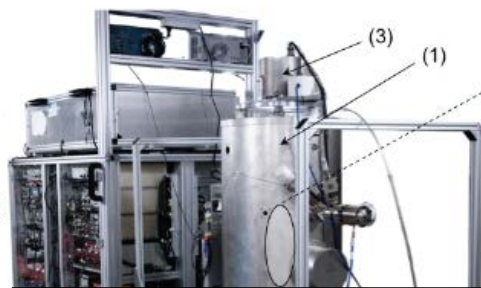
3D mapping and self-attraction

2.0

**Combined**

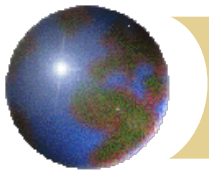
**2.8 / 3.7**

**relative standard uncertainty 2.8E-9 / 3.7E-9**



**Advantage: continuous  $g/g_F$  time series, possibility to invite more AGs, compare them etc.**  
**Disadvantage: SG needs ice-cleaning once/year, cold-head repair each 3-years**





# Conclusion: Accuracy of $g_F$ 2/3

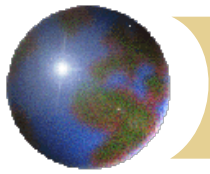
**Absolute method**, based on absolute measurements. Monthly measurements are able to clearly detect the seasonal signal. The **minutes also by an FG5X**

To determine „ $g_F$ “ combination with **models of tides, polar motion, air pressure is efficient**– no need to operate AG exactly at the time of KB experiment



Parameter	Standard uncertainty / $\mu\text{Gal}$
Absolute $g$ : <i>FG5X-HS5 (CAG-01) / FG5X</i>	1.9 / 3.1
Tides	0.2
Polar motion	0.05
Atmosphere	1.0
Seasonal signal	$\approx 1.0$
3D mapping and self-attraction	2.0
<b>Combined</b>	<b>3.1 / 4.0</b>

**Disadvantage: AG offset variations are not controlled, regular validation is needed**



# Conclusion: Accuracy of $g_F$ 3/3

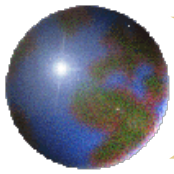
**Minimalistic method**, based on rarely absolute measurements and modelling tides, atmosphere and polar motion effects.

“Seasonal” variations are dangerous:  
- the measured absolute  $g$  (e.g. in spring) might be deviated from the “middle”  
- KB experiment can be done in the opposite season (in autumn)

Maximal systematic error (peak to peak variability of seasonal signal)

Parameter	Standard uncertainty / $\mu\text{Gal}$
Absolute $g$ : <i>FG5X-HS5 (CAG-01) / FG5X</i>	1.9 / 3.1
Tides	0.2
Polar motion	0.05
Atmosphere	1.0
Seasonal signal	??????????
3D mapping and self-attraction	2.0
<b>Combined</b>	<b>&gt;3.1 / &gt;4.0</b>





*Thank you for your attention!*

*New gravity lab at the Pecný station*

