

Report to the 18th CCTF, June 4 2009

Working Group on International Atomic Time

Patrizia Tavella

INRIM Italy



**8th Meeting of representatives of laboratories contributing to TAI
BIPM, 3 June 2009**

75 participants

35 countries

Representatives of Scientific Unions

CCTF Chairman

BIPM staff

About 10 “new” laboratories

Associated or next to be associated countries

8th Meeting of representatives of laboratories contributing to T Education on time scale

BIPM, 3 June 2009

1. Welcome and adoption of the agenda (P. Tavella)
2. Status report from BIPM: TAI, UTC, Terrestrial Time, primary frequency s
3. Being a TAI laboratory: current status and future challenges (P. Tavella) wi
 - time scale steering (D. Matsakis, USNO)
 - redundancy and robustness (M. Hosokawa, NICT)
 - GNSS time transfer (P. Defraigne, ORB)
 - Calibrating a GNSS receiver (J. Levine, NIST)
4. Improvement in the computation of TAI and in contributing laboratories
 - Future plans to improve clock comparison:
 - Precise Point Positioning; results of the pilot experiment (G. F
 - Use of GLONASS for TAI time links (W. Lewandowski, BIP
 - Comparison between time transfer techniques and methods (Z. Jiang, I
 - Report of calibration of time links for TAI (W. Lewandowski and G. P
 - Improving the clock frequency prediction in TAI algorithm (G. Panfilc
 - Data collection and checking (A. Harmegnies, BIPM
5. Report of the sub-group on Algorithms (P. Tavella)
6. Report from the ITU-R discussion on leap second, CCTF le
7. Reports from other CCTF Working Groups
 - WG CGGTTS (J. Levine, NIST)
 - WG TWSTFT (W. Klepczynski, USNO)
 - WG MRA (F. Cordara, INRIM)
 - WG PFS (T. Parker, NIST)

realisation, laboratory practice and algorithm is

Clock and equipment failures difficult to be

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contr Characterisation of relative delay of GNSS receivers still very important. The challenge is

New reducing the uncertainty receiver manufacturers

should be informed on the ransfer and

necessity of external timing ITRF should be used
either with GPS or delay web
GLONASS data

endorsed by BIPM Subsequent delay The work on TAI algorithm

More frequent labor improvement in progress is collection allows the appreciated and encouraged control and speed up UTC computation

Laboratories should get information from IERS on leap seconds

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Main issues:

Education on time scale realisation, laboratory practice and algorithm is requested

Clock and equipment failures difficult to be completely foreseen and controlled

Characterisation of relative delay of GNSS receivers still very important.

The challenge is reducing the uncertainty

New and future GNSS receiver manufacturers should be informed on the necessity of external timing input option

ITRF should be used either with GPS or GLONASS data

Multiple time transfer and delay measurement data available on the BIPM web

A protocol for RMO characterisation of relative delay of GNSS receivers is to be endorsed by BIPM. Subsequent delay compensation common practice to be drafted by BIPM

The work on TAI algorithm improvement in progress is appreciated and encouraged

More frequent laboratory data collection allows the BIPM to improve control and speed up UTC computation

Laboratories should get information from IERS on leap seconds



Fifth International Symposium on Time Scale Algorithms

April 28-30, 2008 at
Real Observatorio de la Armada
San Fernando, Spain

Organized by the *CCTF sub-WG on Algorithms*
chaired by *Patrizia Tavella INRiM*,
in collaboration with *Felicitas Arias BIPM*, *Juan Palacio ROA*,
and *Demetrios Matsakis USNO*



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V International Time Scale Algorithm Symposium, 2008

70 participants

CHINA 9, FINLAND 1, FRANCE 8, GERMANY 4, JAPAN 1, INDIA 3, BIPM 6
ITALY 9, KENIA 1, LATVIA 1, LITHUANIA 1, MEXICO 2, POLAND 1
CZECH REP 1, RUSSIA 3, SPAIN 12, SWITZERLAND 2, USA 5

About 50% from NMI

50% from industries, navigation, telecom...

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